

Localic completion of generalized metric spaces II: Powerlocales

STEVEN VICKERS

The work investigates the powerlocales (lower, upper, Vietoris) of localic completions of generalized metric spaces. The main result is that all three are localic completions of generalized metric powerspaces, on the Kuratowski finite powerset. This is a constructive, localic version of spatial results of Bonsangue et al. and of Edalat and Heckmann.

As applications, a localic completion is always overt, and is compact iff its generalized metric space is totally bounded.

The representation is used to discuss closed intervals of the reals, with the localic Heine–Borel Theorem as a consequence.

The work is constructive in the topos-valid sense.

[54B20](#); [06D22](#), [03G30](#), [54E50](#), [03F60](#)

1 Introduction

In the geometric approach to point-free topology, as outlined in some detail in [32], a prominent place in the reasoning style is occupied by the *powerlocales* (or point-free hyperspaces). There is therefore an intrinsic interest in investigating how powerlocales interact with geometric modes of defining point-free spaces. The present paper studies powerlocales when applied to localic completions [33] of metric spaces (in fact, of generalized metric spaces in the sense of Lawvere [14]), and shows that the powerlocales too are localic completions, got by taking appropriate generalized metrics on the finite powersets of the original spaces.¹

Hyperspaces from the start have been associated with metric spaces. (From the localic point of view, a convenient account of the historical background is given in [7] in its description of the Vietoris powerlocale. Another interesting summary, from the point

¹The core technical content of those results has already appeared in [29].

of view of non-standard analysis, is in [39].) If X is a metric space, then the Hausdorff metric on the powerset $\mathcal{P}X$ is defined by

$$d_H(A, B) = \max(m(A, B), m(B, A))$$

where

$$m(A, B) = \sup_{a \in A} \inf_{b \in B} d(a, b).$$

In this generality we have that m and d_H satisfy the triangle inequality, that $d_H(A, A) = m(A, A) = 0$, and that d_H (though not m) is symmetric. However, they are not metrics as they stand. First, $m(A, B)$ may be infinite if A is unbounded or B is empty. Next, $d_H(A, \text{Cl}(A)) = 0$ where $\text{Cl}(A)$ is the closure of A – indeed, $m(A, B) = 0$ iff $A \subseteq \text{Cl}(B)$. We get a metric space by restricting d_H to the closed, bounded, non-empty subspaces of X .

Restricting to compact non-empty subspaces, the topology induced by the Hausdorff metric can also be got by purely topological means, from the Vietoris topology on $\mathcal{P}X$. This is given by a subbase of opens, comprising sets of the form

$$\begin{aligned} \square U &= \{A \mid A \subseteq U\} \\ \diamond U &= \{A \mid A \cap U \neq \emptyset\} \end{aligned}$$

where U is open in X . This Vietoris topology motivated Johnstone's construction [9] of what we now call the Vietoris powerlocale. (It is also described in preliminary form – with an unnecessary restriction to the compact regular case – in [7], together with detailed historical notes.) The aim of the present paper is to reconstruct in localic terms the connection between Hausdorff metric and Vietoris topology. We shall see the metric reappearing at the level of *finite* subsets of the metric space.

It is also natural to ask how the hyperspace theory might appear in the setting of generalizations such as quasimetrics (for which the symmetry axiom is dropped). In fact the whole of the present paper depends on this, since the upper and lower powerspaces are non-symmetric. Another example is the lower reals (Definition 7.5); in fact non-symmetry goes naturally with non- T_1 spaces (non-discrete specialization order). It is then fruitful to modify the definition of the Hausdorff metric, so that it is not automatically symmetric. If we take m , as defined above, as a *lower* quasimetric d_L on sets, and define an *upper* quasimetric $d_U(A, B) = \sup_{b \in B} \inf_{a \in A} d(a, b)$ (which would equal $m(B, A)$ if d were symmetric), then we can take $d_H(A, B) = \max(d_L(A, B), d_U(A, B))$.

Bonsangue et al. [2] have already studied hyperspaces for Lawvere's generalized metric spaces, in which the only assumptions are zero self-distance and the triangle inequality: the metric may be asymmetric, may take infinite values, and may fail the axiom that if

$d(x, y) = d(y, x) = 0$ then $x = y$. In [2] the approach to hyperspaces is adopted from domain theory, which distinguishes between the convex powerdomain, analogous to the Vietoris hyperspace, and two other “lower” and “upper” powerdomains. Given a complete generalized metric space X , equipped with what they define as a “basis” B , they define the “lower powerdomain” of X as a certain subspace of a continuous dcpo \widehat{B} that can also be understood as the lower powerdomain of a *ball domain*, a continuous dcpo as developed in [3] and [20]. Having defined this lower powerdomain, [2] shows that it can also be got by completing the finite powerset $\mathcal{F}B$ equipped with a “lower metric” (in effect, one part of the Vietoris metric). The paper also sketches similar results for upper and convex powerdomains. To summarize, hyperspaces (powerdomains; lower, upper or convex) of generalized metric space completions can be got as completions of finite powersets equipped with an appropriate generalized metric (lower, upper or convex).

There are analogous constructions in [3] for the convex powerdomain (Vietoris hyperspace) of an ordinary metric space, and there we see extensive use of the ball domain idea. This embeds the metric space as the maximal points in a continuous dcpo of formal balls, the maximal points being balls of zero radius. The idea seems to originate in the interval domain [21], where the same idea is applied to the reals. Once the embedding has been made, techniques of continuous dcpo theory can be applied to gain results about the metric space.

Our companion paper [33] describes a localic treatment of generalized metric space completion: for each generalized metric space X , it defines a locale \overline{X} , its “localic completion”. The points of \overline{X} are Cauchy filters of formal open balls in X . In the symmetric case these are classically equivalent to equivalence classes of Cauchy sequences, and more generally to the elements of the completion described in [2]. However, the descriptions used in [2] and in [33] are radically different. The completion in [2] is a “least subset closed under limits”, and even in classical mathematics it is not amenable to localic development – the classical equivalence proof in [33] is rather intricate. From the localic point of view, the completion by Cauchy filters of formal balls is much more satisfactory, essentially because those Cauchy filters are the models of a propositional geometric theory. (One might argue that in any case the construction is simpler than that in [2].) Moreover, the reasoning is easily done constructively – one great advantage of the localic approach to topology is that it gives better constructive results.

The effect of the present paper is to translate the powerdomain results of [2] into the setting of the localic completion. However, their definitions of powerdomains are replaced by the localic constructions of powerlocales, the localic version of hyperspaces,

and for this reason the technical development here is almost entirely new and somewhat algebraic in nature. There is still a measure of comparison through our use of ball domains, and in that respect the present paper gives a localic account of a generalization (to generalized metric spaces and to all three powerdomains) of [3]. We shall show that the powerlocales of \bar{X} may themselves also be described as localic completions, with respect to three different generalized metrics on the (Kuratowski) finite powerset $\mathcal{F}X$ of X . The Vietoris powerlocale, which is by definition analogous to the Vietoris hyperspace topology, in this situation uses the Hausdorff metric restricted to finite subsets. The lower and upper powerlocales correspond to different topologies with subbases given by the opens $\square U$ and $\diamond U$ respectively. Their corresponding metrics are asymmetric, even for symmetric X .

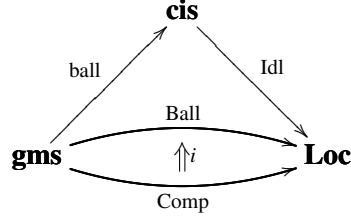
We give two sets of applications. The first exploits the fact that some properties of locales can be expressed as structure existing in the powerlocales. For instance, a locale is compact iff its upper powerlocale is colocal (has, in a certain universal sense, a top point). This then makes it easy to characterize compactness of \bar{X} in terms of a total boundedness property on the generalized metric space X . A similar argument with the lower powerlocale yields the result that all completions \bar{X} are overt (open) as locales, a property that is classically trivial but constructively important.

The second set of applications is to the real line \mathbb{R} , as completion $\bar{\mathbb{Q}}$ of the rationals. Our techniques make it easy to define the closed interval $[0, 1]$ as a point of the Vietoris powerlocale $V\mathbb{R}$, and then its compactness (the Heine–Borel Theorem) follows immediately from the way points of VX (for any locale X) correspond to certain compact sublocales of X . The localic Heine–Borel Theorem is, of course, known already [4], and is a good example of how in constructive mathematics, ordinary topology works better with a point-free approach. With the powerlocales we can strengthen this by defining the interval $[x, y]$ for general $x \leq y$, and indeed we see how $[x, y]$ depends continuously on x and y . This is developed further in [38], with an account of the Intermediate Value Theorem.

The paper is constructive throughout in the sense of topos validity.

1.1 Outline of development

We shall be working within a context of categories



where \mathbf{Loc} , \mathbf{gms} and \mathbf{cis} are the categories of locales, generalized metric spaces and continuous information systems (Sections 2.1, 2.4 and 2.3).

The functor of central interest is the localic completion functor $\text{Comp}(X) = \bar{X}$. Our main result (Theorem 5.4) is that each powerlocale P_{\sim} (lower, upper or Vietoris) applied to a completion \bar{X} can be got by completing an elementary construction based on the finite powerset $\mathcal{F}X$. We find three *powerspace* constructions \mathcal{F}_{\sim} on \mathbf{gms} (Section 3), and natural isomorphisms

$$v_{\sim} : \text{Comp} \circ \mathcal{F}_{\sim} \cong P_{\sim} \circ \text{Comp}.$$

While the diagram is in front of us, let us mention that in our context Comp is not an endofunctor and does not lead to a completion monad over which some power monad might distribute. We do not at present have notions of “generalized metric locale”, or complete such, and Comp acts between two quite distinct categories.

The rest of the diagram concerns tools used in constructing these isomorphisms. These reduce to the similar, but simpler, results [26] for the ideal completion functor $\text{Idl} : \mathbf{cis} \rightarrow \mathbf{Loc}$. They involve constructions \mathcal{F}_{\sim} on \mathbf{cis} (again based on the finite powerset; Proposition 2.11) and natural isomorphisms (Definition 2.12)

$$v'_{\sim} : \text{Idl} \circ \mathcal{F}_{\sim} \cong P_{\sim} \circ \text{Idl}.$$

These are combined using the ball domain idea (Section 4). This can be understood at an elementary level as a functor $\text{ball} : \mathbf{gms} \rightarrow \mathbf{cis}$, under which $\text{ball}(X)$ is an information system of formal balls ordered by refinement. There are again natural transformations

$$\phi_{\sim} : \text{ball} \circ \mathcal{F}_{\sim} \rightarrow \mathcal{F}_{\sim} \circ \text{ball}$$

(Definition 4.4), though this time not isomorphisms. From these we can derive (Definition 4.7)

$$\phi'_{\sim} : \text{Ball} \circ \mathcal{F}_{\sim} \rightarrow P_{\sim} \circ \text{Ball}$$

in which $\text{Ball}(X) = \text{Idl} \circ \text{ball}(X)$ is the ball domain.

We can take ϕ'_{\sim} as already understood, since v'_{\sim} is known from [26] and ϕ_{\sim} is elementary. Our strategy now (Sections 5.1 and 5.2) is to use an embedding $i: \text{Comp} \rightarrow \text{Ball}$ (Definition 4.3) and show how v_{\sim} can be obtained by restricting ϕ'_{\sim} and, moreover, that it becomes a natural isomorphism.

An important fact about the powerlocales is that they are the functor parts of monads (in the categorical sense: see [16]) on \mathbf{Loc} , so it is useful to know that there is also monad structure on the \mathcal{F}_{\sim} constructions and that Comp and Idl preserve it (modulo the isomorphisms v_{\sim} and v'_{\sim}). This last fact can be expressed technically by saying that (Comp, v_{\sim}) and (Idl, v'_{\sim}) are *monad opfunctors* ([23]; see our Section 2.2). That notion does not depend on v_{\sim} and v'_{\sim} being isomorphisms, and in fact it will prove useful to know that $(\text{ball}, \phi_{\sim})$ and $(\text{Ball}, \phi'_{\sim})$ are also monad opfunctors.

1.2 Notation

We mention some notational features of the paper that are not entirely standard.

Composition: The default order for composition of functions or morphisms is the “applicative” order, sometimes emphasized with a \circ symbol. Thus if $f: X \rightarrow Y$ and $g: Y \rightarrow Z$ then $gf = g \circ f: X \rightarrow Z$ with $(g \circ f)(x) = g(f(x))$. Occasionally it is convenient to use the diagrammatic order, and for this the $;$ symbol is adopted from computer programming. Thus $f;g = gf$. For natural transformations the “vertical” composition, got by composing components, is often written vertically. This is explained and illustrated in Section 2.2.

Down closure etc.: Suppose R is a relation from A to B and $B' \subseteq B$. Then RB' denotes the inverse image $\{a \in A \mid \exists b \in B'. aRb\}$. This is particularly useful in association with orders. If \leq is a partial order on A , then $\leq A'$ and $\geq A'$ are the down closure and up closure of A' . Similarly for a non-reflexive order $<$ we might write $< A'$ and $> A'$, though these will no longer include A' and so are not closures.

2 Background

2.1 Locales and powerlocales

For the general background on locales, see [7] or [25]. We shall use extensively the technique that locales and locale maps can be described pointwise, so long as

the description is *geometric*: the points are described as the models of a geometric theory, and a map is described using constructions of geometric constructivism, ie those constructions that are preserved by the inverse image parts of geometric morphisms. Principally, those are colimits, finite limits and free algebra constructions for finitary theories – including the finite powerset, as free semilattice. This is explained rather more carefully in [38]. For technical detail see [32], which also explains how locale constructions (notably powerlocales) may be geometric, as well as other papers such as [36], [30] and [31].

A propositional geometric theory is presented by a set G of propositional symbols, and a set R of axioms of the form $\phi \rightarrow \psi$ where ϕ and ψ are geometric *formulae*: they are built from the propositional symbols using finitary conjunction and arbitrary (possibly infinitary) disjunction. But this is formally equivalent to a presentation $\text{Fr}\langle G \mid R \rangle$ of a frame by generators G and relations R , each axiom $\phi \rightarrow \psi$ being interpreted as a relation $\phi \leq \psi$, with conjunction and disjunction interpreted as frame theoretic meet and join – this frame is the (geometric) *Lindenbaum algebra* of the theory. Algebraically, its universal property is that for any frame A and function $f: G \rightarrow A$ respecting the relations (they become true in A), there is a unique frame homomorphism $f': \text{Fr}\langle G \mid R \rangle \rightarrow A$ that agrees with f on the generators. If G itself has structure of a kind that exists in frames (for example poset, semilattice, lattice), we often write “(qua ... that kind of structure)” to indicate implicit relations requiring the structure of G to be preserved in the frame presented.

The Vietoris powerlocale was introduced in [9]; see also [7]. The upper and lower powerlocales were in effect derived from it, influenced by the parallel development of three *powerdomains* in the denotational semantics of computer programs. The localic connection was made in [40] and [19]. For further remarks on their history see [28], whose technical development we shall largely follow (see also [27]).

Definition 2.1 As in [13], a *suplattice* is a complete join semilattice. A suplattice homomorphism preserves all joins.

As in [12] (and following Banaschewski), a *preframe* is a poset with finite meets and also directed joins, over which the binary meet distributes. A preframe homomorphism preserves the finite meets and directed joins.

Definition 2.2 If X is a locale, then the *lower* and *upper powerlocales* $P_L X$ and $P_U X$ are defined by letting $\Omega P_L X$ and $\Omega P_U X$ be the frames generated freely over ΩX qua suplattice and qua preframe respectively, with generators written as $\diamond a$ and $\square a$ ($a \in \Omega X$). “Qua suplattice” and “qua preframe” say that \diamond preserves joins and \square

preserves finite meets and directed joins. Then if A is any frame and $f: \Omega X \rightarrow A$ is a suplattice homomorphism, then there is a unique frame homomorphism $f': \Omega P_L X \rightarrow A$ such that $f'(\diamond a) = f(a)$, and similarly for preframe homomorphisms and $P_U X$.

The Vietoris powerlocale VX is the ‘‘Vietoris construction’’ of [9]. It is the sublocale of $P_L X \times P_U X$ presented by relations

$$\begin{aligned} \diamond a \times \square b &\leq \diamond(a \wedge b) \times P_U X \\ P_L X \times \square(a \vee b) &\leq \diamond a \odot \square b. \end{aligned}$$

(In a product locale $U \times V$, with $a \in \Omega U$ and $b \in \Omega V$, $a \odot b$ denotes $a \times V \vee U \times b$.) We shall frequently write VX as $P_C X$ to facilitate general arguments that apply to $P_{\sim} X$ where \sim can stand for L, U or C. C here stands for ‘‘convex’’, but this is in a sense of order theory rather than geometry. This is further explained after Theorem 2.3.

The three powerlocales all have *positive* parts. $P_L^+ X$ is the open sublocale $\diamond X$, $P_U^+ X$ is the closed sublocale $P_U X - \square \emptyset$, and $V^+ X$ is the restriction of VX to $P_L^+ X \times P_U^+ X$.

The term ‘‘powerlocale’’ is explained by the fact that their points can be considered as sublocales. The results, all topos-valid, are surveyed in [28]. Sublocales (the localic notion of subspace) are described in the standard texts, but see also [37] for a survey from the geometric point of view.

The global points of $P_U X$ are easily seen to be equivalent to Scott open filters of ΩX , and a localic form (essentially due to Johnstone [9], though the constructive proof [28] is somewhat different) of the Hofmann–Mislove Theorem ([6]; see also [25]) shows that these are exactly the open neighbourhood filters of the compact, fitted sublocales of X . (A sublocale is *fitted* iff it is the sublocale meet of its open neighbourhoods.) Note that the specialization order in $P_U X$ is the opposite of sublocale inclusion: a large Scott open filter corresponds to a small sublocale. \emptyset is the top point in $P_U X$, the Scott open filter containing all the opens of X .

The global points of $P_L X$ are equivalent to the completely prime upsets F in ΩX . Classically, by taking the closed complement of the join of the opens not in F , one finds that these are equivalent to closed sublocales of X . The constructive version is slightly more complicated, and the completely prime upsets are equivalent to overt, weakly closed sublocales of X . (*Overt*ness of locales will be discussed in more detail in Section 6.2. A sublocale of X is weakly closed iff it is a meet of sublocales of the form $(X - U) \vee !^* p$, where U is open and p is a proposition (truth value). $!: X \rightarrow 1$ is the unique map, and so $!^* p$ denotes the sublocale $\bigvee \{X \mid p\}$.) The completely prime upset corresponding to an overt, weakly closed sublocale K comprises the opens of X

that are positive modulo K . The specialization order for $P_L X$ agrees with the inclusion order for sublocales: a large sublocale has more positive opens. \emptyset is the bottom point in $P_L X$.

The global points of VX are equivalent to the compact, overt, weakly semifitted sublocales of X , where a sublocale is weakly semifitted if it is a meet of a fitted sublocale and a weakly closed sublocale.

There are embeddings $\uparrow: X \rightarrow P_U^+ X$, $\downarrow: X \rightarrow P_L^+ X$ and $\{-\}: X \rightarrow V^+ X$, whose inverse image functions take (as appropriate) $\square a$ to a and $\diamond a$ to a . For a point x of X , $\uparrow x$ is the sublocale comprising those points y with $x \sqsubseteq y$, and $\downarrow x$ comprises those with $y \sqsubseteq x$. $\{x\}$ comprises the point x only. We vary this notation by writing $\Downarrow: VX \rightarrow P_L X$ and $\Uparrow: VX \rightarrow P_U X$ for the projection maps restricted to VX .

Theorem 2.3 [27] *Let X be a locale, and let K be a point of $P_{\sim} X$ where \sim is U, L or C . Then the corresponding sublocale of X comprises those points x such that (for the three cases of \sim) –*

- U : $\uparrow x \sqsupseteq K$,
- L : $\downarrow x \sqsubseteq K$, or
- C : $\uparrow x \sqsupseteq \Uparrow K$ and $\downarrow x \sqsubseteq \Downarrow K$.

Note that a sublocale K corresponding to a point of the upper powerlocale $P_U X$ is upper closed with respect to the specialization order: if x is in K and $x \sqsubseteq y$ then y is in K . (This is an immediate consequence of the fact that K is fitted.) Similarly, for $P_L X$ the sublocales are lower closed. For VX (also known as $P_C X$), the sublocales are *order convex* – if $x \sqsubseteq y \sqsubseteq z$ with x and z both in K , then y is in K .

2.2 Monads and monad opfunctors

An important aspect of all three powerlocales, as well as their three positive parts, is that they are the functor parts of monads on the category **Loc** of locales. The units are \uparrow , \downarrow and $\{-\}$. The multiplications are analogues of the union function $\cup: \mathcal{P}\mathcal{P}X \rightarrow \mathcal{P}X$ and, following [27], we write them as $\sqcap: P_U^2 \rightarrow P_U$, $\sqcup: P_L^2 \rightarrow P_L$ and $\cup: V^2 \rightarrow V$. Their inverse image functions take (as appropriate) $\square a$ to $\square \square a$ and $\diamond a$ to $\diamond \diamond a$. In this section we summarize relevant parts of the abstract theory of monads.

The notion of monad itself is familiar from [16], but let us repeat the definition here.

Definition 2.4 Let \mathcal{C} be a category. A *monad* on \mathcal{C} is an endofunctor $T: \mathcal{C} \rightarrow \mathcal{C}$ equipped with two natural transformations $\eta: \mathcal{C} \rightarrow T$ and $\mu: T^2 \rightarrow T$, satisfying the equations

$$\frac{T \mid \eta}{\mu} = \frac{\eta \mid T}{\mu} = T \text{ and } \frac{\mu \mid T}{\mu} = \frac{T \mid \mu}{\mu}.$$

There are some notational conventions here that we shall use throughout. First, we use the name of a category \mathcal{C} also for the identity functor $\text{Id}_{\mathcal{C}}$ on it (as in $\eta: \mathcal{C} \rightarrow T$), and the name of a functor for the identity natural transformation on it (as for both instances of T in $\frac{\eta T}{\mu} = T$). Second, we write horizontal composition of natural transformations horizontally, with the domain on the right, and vertical composition vertically, with the domain at the top. In displayed equations we shall mark these with vertical and horizontal lines, aligned to give an indication of how the domains and codomains match up.

As an example, consider the equation $\frac{\mu T}{\mu} = \frac{T \mu}{\mu}$. The horizontal composite $\mu T: T^3 \rightarrow T^2$ is got by taking components of μ at objects TX , while $T \mu: T^3 \rightarrow T^2$ is got by applying T to components of μ . Now bearing in mind that vertical composition is got by composing components of natural transformations, we see that the equation stands for a commutative diagram as follows (for all X).

$$\begin{array}{ccc} T^3 X & \xrightarrow{\mu_{TX}} & T^2 X \\ T \mu_X \downarrow & & \downarrow \mu_X \\ T^2 X & \xrightarrow{\mu_X} & TX \end{array}$$

Example 2.5 The best known examples of monads on **Set** are those in which TX is a free algebra over X for some given algebraic theory. One that is related to the powerlocales is the free semilattice, given concretely by the finite powerset $\mathcal{F}X$ with \cup as its semilattice operation. (Similarly, the full powerset $\mathcal{P}X$ is the free suplattice.) Functorially, if $f: X \rightarrow Y$ then $\mathcal{F}f$ gives direct images. The unit of the monad is the singleton map $\{-\}: X \rightarrow \mathcal{F}X$, $x \mapsto \{x\}$, and the multiplication is the union map $\bigcup: \mathcal{F}\mathcal{F}X \rightarrow \mathcal{F}X$.

“Finite” here means *Kuratowski finite*: a set is finite if its elements can be listed in a finite list, possibly with repetitions. Note that emptiness of finite sets is a decidable property. We write \mathcal{F}^+X for the set of non-empty finite subsets of X . The monad structure on $\mathcal{F}X$ restricts to one on \mathcal{F}^+X .

We now turn to the monad opfunctors. Street [23] defines, for any 2–category \mathbb{C} , a 2–category $\mathbf{Mnd}(\mathbb{C})$ whose 0–cells, 1–cells and 2–cells are *monads*, *monad functors* and *monad functor transformations*. The paper also introduces dual terminology corresponding to $\mathbf{Mnd}(\mathbb{C}^*)^*$, where \mathbb{C}^* is the dual got by reversing 1–cells, and in fact those monad *opfunctors* will be more relevant to us here. Specializing to the case $\mathbb{C} = \mathbf{Cat}$ we have the following definitions.

Definition 2.6 Suppose \mathcal{C}_i ($i = 1, 2$) are categories, with monads (T_i, η_i, μ_i) . A *monad opfunctor* from (\mathcal{C}_1, T_1) to (\mathcal{C}_2, T_2) is a pair (F, ϕ) where $F: \mathcal{C}_1 \rightarrow \mathcal{C}_2$ is a functor and $\phi: FT_1 \rightarrow T_2F$ is a natural transformation such that

$$\frac{F \mid \eta_1}{\phi} = \eta_2 F \text{ and } \frac{\phi \mid T_1}{T_2 \mid \phi} = \frac{F \mid \mu_1}{\phi}.$$

Given a second monad opfunctor $(G, \psi): (\mathcal{C}_2, T_2) \rightarrow (\mathcal{C}_3, T_3)$, their composite is $(GF, \begin{smallmatrix} G\phi \\ \psi F \end{smallmatrix}): (\mathcal{C}_1, T_1) \rightarrow (\mathcal{C}_3, T_3)$.

If (F, ϕ) and (F', ϕ') are two monad opfunctors from (\mathcal{C}_1, T_1) to (\mathcal{C}_2, T_2) , then a *monad opfunctor transformation* from (F, ϕ) to (F', ϕ') is a natural transformation $\alpha: F \rightarrow F'$ such that $\begin{smallmatrix} \alpha T_1 \\ \phi' \end{smallmatrix} = \begin{smallmatrix} \phi \\ T_2 \alpha \end{smallmatrix}$.

The dual terminology is similar. A *monad functor* from (\mathcal{C}_1, T_1) to (\mathcal{C}_2, T_2) is a pair (F, ψ) where $F: \mathcal{C}_1 \rightarrow \mathcal{C}_2$ is a functor and $\psi: T_2F \rightarrow FT_1$ is a natural transformation such that the corresponding dual equations hold. Transformations of monad functors are defined similarly to those for monad opfunctors.

If ϕ is a natural isomorphism, then (F, ϕ) is a monad opfunctor iff (F, ϕ^{-1}) is a monad functor and these are equivalent ways of saying that F preserves the monad structure modulo the isomorphism. Our main result (Theorem 5.4) is that localic completion does this, with respect to the powerspace and powerlocale monads, and as such it could be stated in terms of either monad functors or monad opfunctors. However, as mentioned already in Section 1.1, along the way we find ourselves using transformations ϕ that are not isomorphisms but still give monad opfunctors. Hence we see monad opfunctors as a kind of symmetry breaking of the main idea of preserving monad structure modulo isomorphism.

As an exercise, the reader unfamiliar with the 2–dimensional calculus might like to

verify that the equation $\begin{smallmatrix} \phi T_1 \\ T_2 \phi \\ \mu_2 F \end{smallmatrix} = \begin{smallmatrix} F \mu_1 \\ \phi \end{smallmatrix}$ above stands for a commutative diagram as

follows (for all X).

$$\begin{array}{ccccc}
 FT_1^2X & \xrightarrow{\phi_{T_1X}} & T_2FT_1X & \xrightarrow{T_2\phi_X} & T_2^2FX \\
 \downarrow F(\mu_1)_X & & & & \downarrow (\mu_2)_{FX} \\
 FT_1X & \xrightarrow{\phi_X} & T_2FX & &
 \end{array}$$

Next we prove some abstract lemmas that will be useful later.

Lemma 2.7 *Let $(F, \phi): (\mathcal{C}_1, T_1) \rightarrow (\mathcal{C}_2, T_2)$ be a monad opfunctor. Let $G: \mathcal{C}_1 \rightarrow \mathcal{C}_2$, and let $i: G \rightarrow F$ be such that each component of T_2i is monic. For each object X of \mathcal{C}_1 let $\psi_X: GT_1X \rightarrow T_2GX$ be such that the following diagram commutes.*

$$\begin{array}{ccc}
 GT_1X & \xrightarrow{i_{T_1X}} & FT_1X \\
 \psi_X \downarrow & & \downarrow \phi_X \\
 T_2GX & \xrightarrow{T_2i_X} & T_2FX
 \end{array}$$

Then (G, ψ) is a monad opfunctor and $i: (G, \psi) \rightarrow (F, \phi)$ is a transformation of monad opfunctors.

Proof A simple diagram chase shows that ψ is natural, and then it is immediate that i satisfies the conditions for a transformation of monad opfunctors. Next, we have

$$\frac{G \mid \eta_1}{T_2 \mid i} = \frac{G \mid \eta_1}{i \mid T_1} = \frac{i}{F \mid \eta_1} = \frac{i}{\eta_2 \mid F} = \frac{\eta_2 \mid G}{T_2 \mid i}$$

and hence $\frac{G\eta_1}{\psi} = \eta_2G$. Next,

$$\begin{aligned}
 \frac{G \mid \mu_1}{T_2 \mid i} &= \frac{G \mid \mu_1}{i \mid T_1} = \frac{i \mid T_1 \mid T_1}{F \mid \mu_1} = \frac{i \mid T_1 \mid T_1}{T_2 \mid \phi} = \frac{\psi \mid T_1}{T_2 \mid i} \\
 &= \frac{\psi \mid T_1}{T_2 \mid \psi} = \frac{\psi \mid T_1}{\mu_2 \mid G} = \frac{\psi \mid T_1}{\mu_2 \mid i}
 \end{aligned}$$

so

$$\frac{G \mid \mu_1}{\psi} = \frac{\psi \mid T_1}{T_2 \mid \psi} \cdot \frac{\mu_2 \mid G}{\psi}$$

(Readers unfamiliar with this kind of vertical calculus can prove the result by diagram chasing.) \square

Lemma 2.8 *Let $(F, \phi), (G, \psi), (G', \psi') : (\mathcal{C}_1, T_1) \rightarrow (\mathcal{C}_2, T_2)$ be three monad opfunctors, and consider a diagram*

$$\begin{array}{ccc} (F, \phi) & & \\ \downarrow \beta & \searrow \beta' & \\ (G, \psi) & \xrightarrow{\alpha} & (G', \psi') \end{array}$$

in which –

- β' and α are transformations of monad opfunctors,
- β is a natural transformation of functors,
- the diagram commutes at the level of natural transformations of functors, and
- every component of $T_2\alpha$ is monic.

Then β is a transformation of monad opfunctors.

Proof

$$\frac{\beta \mid T_1}{T_2 \mid \alpha} = \frac{\beta \mid T_1}{\alpha \mid \psi'} = \frac{\beta' \mid T_1}{\psi'} = \frac{\phi}{T_2 \mid \beta'} = \frac{\phi}{T_2 \mid \beta} \cdot \frac{\beta}{\alpha}$$

and hence $\frac{\beta T_1}{\psi} = \frac{\phi}{T_2 \beta}$. \square

2.3 Continuous dcpos and their powerlocales

When discussing the powerlocales, we shall find it useful to embed localic completions in (the localic form of) *continuous dcpos* (see, eg, [5]). For these, the powerlocales are well understood and constructed using finite powersets.

The usual definition is as follows. First, a poset (P, \sqsubseteq) is *directed complete* (or a *dcpo*) if it has all directed joins. We write $\bigsqcup_i^\uparrow x_i$ for a directed join, the “ \uparrow ” signifying that the family of x_i s is indeed directed. If $x, y \in P$, we say x is *way below* y , and write $x \ll y$, if whenever $y \sqsubseteq \bigsqcup_i^\uparrow z_i$ then $x \sqsubseteq z_i$ for some i . Then a dcpo P is a *continuous dcpo* (or a *domain*) if for every $y \in P$ we have

$$y = \bigsqcup_i^\uparrow (\ll y).$$

(Recall the notation from Section 1.2: $\ll y$ is $\{x \mid x \ll y\}$.) The default topology on a dcpo is the Scott topology, for which a subset U is open if it is an upset and inaccessible by directed joins – ie if $\bigsqcup_i^\uparrow x_i \in U$ then $x_i \in U$ for some i .

We shall use the localic theory of continuous dcpos, with the characterization of [26] using continuous information systems.

Definition 2.9 A *continuous information system* (or *cis* or *infosys*) is a set D equipped with an idempotent (transitive and interpolative) relation \prec .

A *homomorphism* between continuous information systems is a function that preserves \prec . We get a category **cis** of continuous information systems and homomorphisms.

An *ideal* of (D, \prec) is a directed lower subset $I \subseteq D$: in detail,

- (1) I is a lower set ($\prec I \subseteq I$).
- (2) I is inhabited (nullary directedness).
- (3) If $s_1, s_2 \in I$ then there is some $s \in I$ with $s_1 \prec s$ and $s_2 \prec s$ (binary directedness). (Consequently, I is *rounded*, ie $I \subseteq \prec I$.)

We write $\text{Idl}(D, \prec)$ (or often just $\text{Idl}(D)$) for the locale whose points are the ideals of (D, \prec) . We can then present

$$\begin{aligned} \Omega \text{Idl}(D, \prec) &\cong \text{Fr}(\uparrow s \ (s \in D) \mid \mathbf{true} \leq \bigvee_{s \in D} \uparrow s \\ &\quad \uparrow s \wedge \uparrow t = \bigvee \{ \uparrow u \mid s \prec u, t \prec u \}). \end{aligned}$$

We say a *locale* is a continuous dcpo if it is homeomorphic to one of the form $\text{Idl}(D, \prec)$. (Note that this is not the same as saying that its frame is a continuous dcpo. In fact [26], a locale is a continuous dcpo iff its frame is constructively completely distributive – such frames are the Stone duals of continuous dcpos.)

Proposition 2.10 *Let $f: (D, \prec) \rightarrow (E, \prec)$ be a homomorphism of continuous information systems. Then we have a map $\text{Idl}(f): \text{Idl } D \rightarrow \text{Idl } E$,*

$$\text{Idl}(f)(I) = \prec f(I)$$

where $f(I)$ denotes the direct image. In terms of opens, we have

$$\text{Idl}(f)^*(\uparrow t) = \bigvee \{\uparrow s \mid t \prec f(s)\}.$$

Proof It is straightforward to check that if I is an ideal of D then $\text{Idl}(f)(I)$ as defined above is an ideal of E . \square

This gives a functor $\text{Idl}: \mathbf{cis} \rightarrow \mathbf{Loc}$.

By [26], each powerlocale $P_{\sim} \text{Idl}(D, \prec)$ is homeomorphic to $\text{Idl}(\mathcal{F}D, \prec_{\sim})$ for a suitable idempotent order on the Kuratowski finite powerset $\mathcal{F}D$.

- The *lower* order has $S \prec_L T$ iff $\forall s \in S. \exists t \in T. s \prec t$.
- The *upper* order has $S \prec_U T$ iff $\forall t \in T. \exists s \in S. s \prec t$.
- The *convex* order has $S \prec_C T$ iff $S \prec_L T$ and $S \prec_U T$.

The notation \prec_L , \prec_U and \prec_C will be used uniformly by applying those subscripts to binary relations. Note that $(\prec_U)^{op} = (\prec^{op})_L$ (or \succ_L). This gives a useful duality principle.

Proposition 2.11 *We have three monads \mathcal{F}_{\sim} on \mathbf{cis} , given by*

$$\mathcal{F}_{\sim}(D, \prec) = (\mathcal{F}D, \prec_{\sim}).$$

In each case, the unit and multiplication of the monad are the same as those for the \mathcal{F} monad on \mathbf{Set} (see Example 2.5).

Proof Checking is routine. One must check (i) \mathcal{F}_{\sim} is functorial, and (ii) $\{-\}$ and \cup are homomorphisms. Once these are done for \mathcal{F}_L , they follow for \mathcal{F}_U by duality, and then for \mathcal{F}_C by combining the two. \square

Definition 2.12 *If (D, \prec) is a continuous information system then we define a map $v'_{\sim}: \text{Idl } \mathcal{F}_{\sim}(D, \prec) \rightarrow P_{\sim} \text{Idl}(D, \prec)$ by*

$$v'_{\sim}(\diamond \uparrow s) = \bigvee \{\uparrow T \mid \{s\} \prec_{\sim} T\} \quad (\sim \text{ stands for L or C})$$

$$v'_{\sim}(\square \bigvee_{s \in S} \uparrow s) = \bigvee \{\uparrow T \mid S \prec_{\sim} T\} \quad (\sim \text{ stands for U or C; } S \in \mathcal{F}D).$$

Since the opens $\uparrow s$ form a base for $\text{Idl}(D, \prec)$, and \diamond preserves joins, it suffices to define $v_{\sim}^*(\diamond U)$ for basic U . However, note that we also have

$$\begin{aligned} v_{\sim}^*(\bigwedge_{s \in S} \diamond \uparrow s) &= \bigwedge_{s \in S} \bigvee \{ \uparrow T \mid \{s\} \prec_L T \} \\ &= \bigvee \{ \uparrow T \mid \text{for each } s \text{ we have } T_s \text{ with } \{s\} \prec_L T_s \prec_{\sim} T \} \\ &= \bigvee \{ \uparrow T \mid S \prec_L T \}, \end{aligned}$$

thus giving a formal similarity with the \square case. Since \square preserves directed joins, it suffices to define $v_{\sim}^*(\square U)$ for U a finite join of basics.

[26, Theorem 4.3] shows that v_{\sim}' is a homeomorphism. The proof there is readily made topos-valid. (It uses cardinality of finite sets and decidable equality for their elements. However, this can easily be remedied by replacing the finite set with an enumeration, possibly with repetitions, of the elements.) The inverses for v_{\sim}^* are given by

$$\uparrow S \mapsto \begin{cases} \bigwedge_{s \in S} \diamond \uparrow s & \text{(for L)} \\ \square(\bigvee_{s \in S} \uparrow s) & \text{(for U)} \\ \square(\bigvee_{s \in S} \uparrow s) \wedge \bigwedge_{s \in S} \diamond \uparrow s & \text{(for C)} \end{cases}$$

Note that this proves that the class of continuous dcpos is closed under the powerlocales.

We show how this translates into actions on ideals.

Lemma 2.13 *Let (D, \prec) be a continuous information system, let I be an ideal of $(\mathcal{F}D, \prec_{\sim})$, and let $S \in \mathcal{F}D$.*

- (1) *(\sim is L or C) I is in the open $\bigwedge_{s \in S} \diamond \uparrow s$ for $P_{\sim} \text{Idl}(D)$ iff $S \in \prec_L I$.*
- (2) *(\sim is U or C) I is in the open $\square(\bigvee_{s \in S} \uparrow s)$ for $P_{\sim} \text{Idl}(D)$ iff $S \in \prec_U I$.*

Note that if \sim is L or U we have $\prec_L I$ and $\prec_U I$ (respectively) equal to I .

Proof The proof of [26, Theorem 4.3] deals explicitly with the Vietoris powerlocale where \sim is C. From it we see that $\diamond \uparrow s$ corresponds to $\bigvee \{ \uparrow T \mid T \cap (\succ s) \neq \emptyset \}$, which equals $\bigvee \{ \uparrow T \mid \{s\} \prec_L T \}$. Now I is in the open $\uparrow T$ iff $T \in I$, and so we can deduce that I is in $\diamond \uparrow s$ iff $\{s\} \prec_L T$ for some $T \in I$. The first condition readily follows. Similarly, $\square(\bigvee_{s \in S} \uparrow s)$ corresponds to $\bigvee \{ \uparrow T \mid T \subseteq \succ S \}$, which equals $\bigvee \{ \uparrow T \mid S \prec_U T \}$.

[26] leaves to the reader the easier cases of the lower and upper powerlocales, but they yield the same conditions. \square

Note the empty point for each powerlocale. For the lower, it is $I = \{\emptyset\}$ (every ideal contains \emptyset); for the upper it is $I = \mathcal{F}X$ (if an ideal contains \emptyset then it contains every finite set); for the Vietoris it is $\{\emptyset\}$ (an ideal can contain *either* \emptyset *or* non-empty sets, but not both). Excluding the empty set, we find that v'_\sim also gives a homeomorphism $\text{Idl } \mathcal{F}_\sim^+(D, \prec) \cong P_\sim^+ \text{Idl}(D, \prec)$.

Proposition 2.14 $(\text{Idl}, v'_\sim): (\mathbf{cis}, \mathcal{F}_\sim) \rightarrow (\mathbf{Loc}, P_\sim)$ is a monad opfunctor.

Proof Using Proposition 2.10 and Lemma 2.13, it is easily checked on inverse image functions that v'_\sim is natural and that the conditions of Definition 2.6 are satisfied. \square

We shall also need the following.

Lemma 2.15 Let (D, \prec) be a continuous information system.

- (1) The map $\Downarrow: V\text{Idl}(D) \rightarrow P_L \text{Idl}(D)$ maps each ideal I of $(\mathcal{F}D, \prec_C)$ to $\prec_L I$.
- (2) The map $\Uparrow: V\text{Idl}(D) \rightarrow P_U \text{Idl}(D)$ maps each ideal I of $(\mathcal{F}D, \prec_C)$ to $\prec_U I$.

Proof 1. Using Lemma 2.13 we have $S \in \Downarrow I$ iff $\Downarrow I$ is in $\bigwedge_{s \in S} \diamond \uparrow s$, ie iff I is in $\bigwedge_{s \in S} \diamond \uparrow s$ since the inverse image function $\Omega \Downarrow$ takes each generator $\diamond U$ in the lower powerlocale to the one with the same name in the Vietoris. From Lemma 2.13 again this is equivalent to $S \in \prec_L I$.

2. This is similar. \square

2.4 Generalized metric completion

We now summarize the account of localic completion that appears in [33]. The description there is in terms of “spaces”, on the understanding that classical mathematicians can interpret it in the conventional way, while locale theorists can read in a localic interpretation as described above. In the present paper our results are unavoidably localic, so we shall write of locales throughout.

\mathcal{Q}_+ is the set of positive rationals.

$\overleftarrow{[-\infty, \infty]}$ is the locale whose points are extended “upper reals”, ie rounded upper sets of rationals. Classically, the *finite* upper reals (ie those for which the rounded upper set of rationals is inhabited but not the whole of \mathbb{Q}) are equivalent to ordinary reals, ie Dedekind sections. Constructively, however, there may be finite upper reals for

which there is no corresponding lower set of rationals to make a Dedekind section. The arrow indicates the direction of the specialization order \sqsubseteq . This is the reverse of the numerical order \leq ($-\infty$ is top for \sqsubseteq), because a large upper set of rationals denotes a numerically small upper real. We shall be particularly interested in $\overleftarrow{[0, \infty]}$, the locale of non-negative, extended upper reals, whose points are rounded upper sets of positive rationals.

The continuous arithmetic structure on $\overleftarrow{[0, \infty]}$ includes order, addition and multiplication, finitary max and min, and infinitary inf. It does not include any kind of subtraction (which would have to be contravariant in one argument, whereas continuous maps must preserve specialization order), or infinitary sup.

We now give the definition from [14], but using the locale $\overleftarrow{[0, \infty]}$ for the reals.

Definition 2.16 A *generalized metric space* (or *gms*) is a set X equipped with a *distance* map $X(-, -): X^2 \rightarrow \overleftarrow{[0, \infty]}$ satisfying

$$\text{(zero self-distance)} \quad X(x, x) = 0$$

$$\text{(triangle inequality)} \quad X(x, z) \leq X(x, y) + X(y, z)$$

(By *map* we mean continuous map, between locales. We are treating the set X^2 as the corresponding discrete locale.)

If X and Y are two gms's, then a *homomorphism* from X to Y is a non-expansive function, ie a function $f: X \rightarrow Y$ such that $Y(f(x_1), f(x_2)) \leq X(x_1, x_2)$. We write **gms** for the category of generalized metric spaces and homomorphisms.

The *opposite* gms X^{op} has $X^{op}(x, y) = X(y, x)$.

Remark 2.17 There is a predicate geometric theory whose models are the generalized metric spaces, and our notion of homomorphism is the natural one in that context.

Definition 2.18 If X is a generalized metric space then we introduce the symbol " $B_\delta(x)$ ", a "formal open ball", as alternative notation for the pair $(x, \delta) \in X \times Q_+$. We write

$$B_\varepsilon(y) \subset B_\delta(x) \text{ if } X(x, y) + \varepsilon < \delta$$

(in other words, if $\varepsilon < \delta$ and $X(x, y) < \delta - \varepsilon$) and say in that case that $B_\varepsilon(y)$ *refines* $B_\delta(x)$.

Definition 2.19 Let X be a generalized metric space. A subset F of $X \times Q_+$ is a *Cauchy filter* if –

- (1) F is *upper* with respect to \subset , ie if $B_\varepsilon(y) \subset B_\delta(x)$ and $B_\varepsilon(y) \in F$ then $B_\delta(x) \in F$.
- (2) If $B_\delta(x) \in F$ and $B_{\delta'}(x') \in F$ then there is some $B_\varepsilon(y) \in F$ with $B_\varepsilon(y) \subset B_\delta(x)$ and $B_\varepsilon(y) \subset B_{\delta'}(x')$.
- (3) For every $\delta \in Q_+$ there is some $x \in X$ such that $B_\delta(x) \in F$.

Definition 2.20 [33] Let X be a generalized metric space. Then its *localic completion* \bar{X} (or $\text{Comp}(X)$) is the locale whose points are the Cauchy filters of formal open balls. If $f: X \rightarrow Y$ is a gms homomorphism then $\text{Comp}(f) = \bar{f}: \bar{X} \rightarrow \bar{Y}$ is defined by

$$\bar{f}(F) = \sup \{B_\delta(f(x)) \mid B_\delta(x) \in F\}.$$

These together give a functor $\text{Comp}: \mathbf{gms} \rightarrow \mathbf{Loc}$.

Proposition 2.21 Let $f, g: X \rightarrow Y$ be homomorphisms of gms's such that for all $x \in X$, $Y(f(x), g(x)) = 0$. Then $\bar{f} \sqsubseteq \bar{g}$.

Proof Suppose F is a Cauchy filter for X and $B_\varepsilon(y) \in \bar{f}(F)$ with $B_\varepsilon(y) \supset B_\delta(f(x))$, $B_\delta(x) \in F$. Then

$$Y(y, g(x)) + \delta \leq Y(y, f(x)) + Y(f(x), g(x)) + \delta = Y(y, f(x)) + \delta < \varepsilon$$

so $B_\varepsilon(y) \supset B_\delta(g(x))$ and $B_\varepsilon(y) \in \bar{g}(F)$. □

Definition 2.22 Let X be a generalized metric space. A subset F of $X \times Q_+$ is a *left X -module* if it is a rounded upper set of formal open balls –

- (1) F is *upper* with respect to \subset (as in Definition 2.19).
- (2) F is *rounded*, ie if $B_\delta(x) \in F$ then there is some $B_\varepsilon(y) \in F$ with $B_\varepsilon(y) \subset B_\delta(x)$.

We write $X\text{-Mod}$ for the locale whose points are the left X -modules.

(The term “module” is explained in [33] in terms of Lawvere’s use of enriched categories. In the present paper those ideas are less relevant but we keep the term.)

3 Powerspaces

If X is a gms, we shall define three *powerspaces* $\mathcal{F}_{\sim}X$ on it, where \sim can stand for L (*lower*), U (*upper*) or C (*convex*, or the *Vietoris* powerspace). They are defined by

three generalized metrics on the finite powerset $\mathcal{F}X$,

$$\begin{aligned}\mathcal{F}_L X(S, T) &= \max_{x \in S} \min_{y \in T} X(x, y) \\ \mathcal{F}_U X(S, T) &= \max_{y \in T} \min_{x \in S} X(x, y) \\ \mathcal{F}_C X(S, T) &= \max(\mathcal{F}_L X(S, T), \mathcal{F}_U X(S, T)).\end{aligned}$$

The finite sets S and T may be empty. We have $\mathcal{F}_L X(\emptyset, T) = 0$ for all T , and $\mathcal{F}_L X(S, \emptyset) = \infty$ if S is non-empty. $\mathcal{F}_U X$ is similar but the other way round, and $\mathcal{F}_C X(S, T) = \infty$ if just one of S, T is empty, but 0 if both are (fortunately for the zero self-distance law).

Clearly $\mathcal{F}_C X$ is the Hausdorff metric restricted to finite sets – hence it is calculated in a finitary way, without recourse to limits. The other two are less familiar but clearly derive from separating out parts of the Hausdorff metric.

A useful duality principle is that $\mathcal{F}_U X = (\mathcal{F}_L(X^{op}))^{op}$.

If X is symmetric then so is $\mathcal{F}_C X$, but the other two are not.

We write $\mathcal{F}_{\sim}^+ X$ for the three *positive* powerspaces, ie restricted to non-empty finite subsets.

Proposition 3.1 *The monad structure of \mathcal{F} extends to all three powerspaces, giving monads on gms.*

Proof We need to check that the functions involved are non-expansive. First, the unit $\{-\}: X \rightarrow \mathcal{F}X$ is obviously an isometry for all three.

For the rest, we first consider \mathcal{F}_L . The multiplication $\bigcup: \mathcal{F}^2 X \rightarrow \mathcal{F}X, \mathcal{U} \mapsto \bigcup \mathcal{U}$, is a homomorphism (non-expansive) because

$$\begin{aligned}\mathcal{F}_L^2 X(\mathcal{U}, \mathcal{V}) < q &\iff \forall U \in \mathcal{U}. \exists V \in \mathcal{V}. \mathcal{F}_L X(U, V) < q \\ &\iff \forall U \in \mathcal{U}. \exists V \in \mathcal{V}. \forall u \in U. \exists v \in V. X(u, v) < q \\ &\implies \forall U \in \mathcal{U}. \forall u \in U. \exists V \in \mathcal{V}. \exists v \in V. X(u, v) < q \\ &\iff \forall u \in \bigcup \mathcal{U}. \exists v \in \bigcup \mathcal{V}. X(u, v) < q \\ &\iff \mathcal{F}_L X(\bigcup \mathcal{U}, \bigcup \mathcal{V}) < q.\end{aligned}$$

Now if $f: X \rightarrow Y$ is a homomorphism then so is $\mathcal{F}f$ (where $\mathcal{F}f(S)$ is the direct image $f(S)$) because

$$\begin{aligned} \mathcal{F}_L X(S, T) < q &\iff \forall x \in S. \exists y \in T. X(x, y) < q \\ &\implies \forall x \in S. \exists y \in T. Y(f(x), f(y)) < q \\ &\iff \forall x' \in \mathcal{F}f(S). \exists y' \in \mathcal{F}f(T). Y(x', y') < q \\ &\iff \mathcal{F}_L Y(\mathcal{F}f(S), \mathcal{F}f(T)) < q \end{aligned}$$

The corresponding results for the upper metric follow by duality, and then those for the Vietoris metric are immediate. \square

4 The ball domain

A technique pioneered in [3] (working classically) is to prove results about complete metric spaces by embedding them in continuous dcpos, the *ball domains*, so that limits in the metric space can be found using directed joins in the dcpo. A simple example then is that the Banach fixed point theorem follows easily from the dcpo fixed point theorems. They also deal with compact subspaces by using powerdomain techniques on the ball domain. Our working will depend on an analogous construction, the principal benefit being to allow us to exploit the way powerlocales are constructed for continuous dcpos. Ball domains for gms's have also been described in [20], and we shall compare our construction with the work there.

If X is a metric space, then Edalat and Heckmann [3] define the *ball domain* $\mathbf{B}(X)$ to be the product $X \times [0, \infty)$, ordered by the non-strict analogy of our \supset on $X \times Q_+$. They call the elements of $\mathbf{B}(X)$ *formal balls* on X . Although $\mathbf{B}(X)$ is not a dcpo in general, they define a Scott topology on it and show (theorem 13) that X embeds in it as the maximal elements $(x, 0)$. Moreover, they define the way below relation and show (section 2.6) that the metric completion \bar{X} embeds in the ideal completion of $\mathbf{B}(X)$ with respect to way below.

Clearly their formal balls are more general than ours in allowing radii that are 0 or irrational. Our ball domain will go further than theirs by allowing centres to be in the completed space. In other words, in a single step we shall complete on both radii and centres.

Note the elementary fact that \subset and \supset are idempotent relations on $X \times Q_+$. We shall write $\text{ball}(X)$ for the continuous information system $(X \times Q_+, \supset)$. This extends to a functor $\text{ball}: \mathbf{gms} \rightarrow \mathbf{cis}$, by $\text{ball}(f)(B_\delta(x)) = B_\delta(f(x))$.

Definition 4.1 The *ball domain* functor $\text{Ball}: \mathbf{gms} \rightarrow \mathbf{Loc}$ is $\text{Idl} \circ \text{ball}$.

In practice it is more natural to view the points of the ball domain as *filters* of $X \times Q_+$ with respect to \subset , rather than ideals with respect to \supset .

Proposition 4.2 A point of $\text{Ball}(X)$ is a subset G of $X \times Q_+$ satisfying the conditions (1) and (2) of Definition 2.19, and in addition that for some δ there is x with $B_\delta(x) \in G$.

Proof Condition (1) says that G is rounded lower with respect to \supset , (2) is binary directedness and the new condition is nullary directedness, ie inhabitedness. \square

Hence \bar{X} embeds as a sublocale of the continuous dcpo $\text{Ball}(X)$, and in turn $\text{Ball}(X)$ embeds as a sublocale of $X\text{-Mod}$ (Definition 2.22). The points of $X\text{-Mod}$ are the rounded upper sets of balls, those of $\text{Ball}(X)$ are the filters, and those of \bar{X} are the Cauchy filters.

Definition 4.3 We write $i: \text{Comp} \rightarrow \text{Ball}$ for the natural transformation whose component at a gms X is the embedding $\bar{X} \hookrightarrow \text{Ball}(X)$.

Definition 4.4 For any gms X , we define $\phi: \mathcal{F}X \times Q_+ \rightarrow \mathcal{F}(X \times Q_+)$ by $\phi(B_\varepsilon(S)) = \{B_\varepsilon(x) \mid x \in S\}$.

Lemma 4.5 If $B_\delta(S) \supset B_\varepsilon(T)$ (with respect to the metric on $\mathcal{F}_\sim X$, where \sim is L, U or C), then $\phi(B_\delta(S)) \supset_\sim \phi(B_\varepsilon(T))$. If we are given that $\varepsilon < \delta$ then the converse also holds.

Proof We have $\mathcal{F}_\sim X(S, T) + \varepsilon < \delta$. First, when \sim is L the condition is equivalent to $\varepsilon < \delta$ and

$$\forall x \in S. \exists y \in T. B_\delta(x) \supset B_\varepsilon(y),$$

and these together imply $\phi(B_\delta(S)) \supset_L \phi(B_\varepsilon(T))$ – in fact, if we are given that $\varepsilon < \delta$ then the reverse implication also holds. (If S is non-empty, then $\phi(B_\delta(S)) \supset_L \phi(B_\varepsilon(T))$ already implies $\varepsilon < \delta$. However, for the lower order, we have $\phi(B_\delta(\emptyset)) \supset_L \phi(B_\varepsilon(T))$ for all δ, ε, T .) The case when \sim is U can be proved either similarly or by duality, and then the case when \sim is C follows. \square

Proposition 4.6 (ball, ϕ_\sim) is a monad opfunctor from $(\mathbf{gms}, \mathcal{F}_\sim)$ to $(\mathbf{cis}, \mathcal{F}_\sim)$.

Proof Lemma 4.5 shows that each component of ϕ_{\sim} is a homomorphism of continuous information systems, and then naturality is easily checked. The rest is routine checking. \square

Definition 4.7 The monad opfunctor $(\mathbf{Ball}, \phi'_{\sim}): (\mathbf{gms}, \mathcal{F}_{\sim}) \rightarrow (\mathbf{Loc}, P_{\sim})$ is defined as the composite of $(\mathbf{ball}, \phi_{\sim})$ and $(\mathbf{Idl}, v'_{\sim})$.

Thus $\phi'_{\sim} = \frac{\mathbf{Idl} \phi_{\sim}}{v'_{\sim} \mathbf{ball}} : \mathbf{Ball}(\mathcal{F}_{\sim} X) \rightarrow P_{\sim} \mathbf{Ball}(X)$, so $\phi'_{\sim}(X)(I) = (\sqsupset_{\sim} \phi(I))$, where $\phi(I)$ is the direct image.

We finish this section by showing how our ball domain relates classically to those of [3] and [20]. The projection $X \times Q_+ \rightarrow Q_+$ is a cis-homomorphism, and so lifts to a *radius* map $r: \mathbf{Ball}(X) \rightarrow \overleftarrow{[0, \infty)} = \mathbf{Idl}(Q_+, >)$ by $r(G) = \inf\{q \mid B_q(x) \in G\}$, an upper real. Lifting the cis-homomorphism $(X \times Q_+) \times Q_+ \rightarrow X \times Q_+$, $(B_{\delta}(x), q) \mapsto B_{\delta+q}(x)$, we also obtain a map $+: \mathbf{Ball}(X) \times \overleftarrow{[0, \infty)} \rightarrow \mathbf{Ball}(X)$, defined by

$$G + a = \{B_{\delta+q}(x) \mid B_{\delta}(x) \in G, a < q\}.$$

Note that $r(G + a) = r(G) + a$, and G is Cauchy iff $r(G) = 0$.

Proposition 4.8 (Classically) *Let X be a gms. Then the map $+: \overline{X} \times \overleftarrow{[0, \infty)} \rightarrow \mathbf{Ball}(X)$ is a bijection on points.*

Proof Let G be a filter in $X \times Q_+$. We define its *centre* $c(G)$ to be $\{B_{\delta}(x) \mid \exists B_q(x) \in G. q - \delta < r(G)\}$. (Note – constructively, the upper real $r(G)$ is approximated from above. It is therefore constructively illegitimate to use approximations from below, as in $q - \delta < r(G)$.)

If F is a Cauchy filter and a is a non-negative upper real, then $c(F + a) = F$, ie

$$B_{\delta}(x) \in F \iff \exists \delta', q. (B_{\delta'}(x) \in F \text{ and } \delta' + q - \delta < a < q).$$

The \Leftarrow direction follows because $\delta' < \delta$. For \Rightarrow , we can find $\delta' < \delta$ such that $B_{\delta'}(x) \in F$, and then q such that $q - (\delta - \delta') < a < q$.

Now suppose G is a filter in $X \times Q_+$. We must show $G = c(G) + r(G)$, which works out as equivalent to

$$B_q(x) \in G \iff \exists \delta, q'. (B_{q'}(x) \in G \text{ and } q' - \delta < r(G) < q - \delta).$$

\Leftarrow is obvious. For \Rightarrow , find $q' < q$ such that $B_{q'}(x) \in G$ and then r such that $r - (q - q') < r(G) < r < q$, and then put $\delta = q - r$. \square

Of course, the map $+$ is not a homeomorphism. As can easily be seen from the case of symmetric X , the specialization orders on $\overline{X} \times \overline{[0, \infty)}$ and $\mathbf{Ball}(X)$ are different. The classical result shows that for symmetric X , the points of our $\mathbf{Ball}(X)$ are the same as those of the ball domain $\mathbf{B}(\overline{X})$ in [3].

We should also compare our formal balls with those of [20], which deals with the gms case (albeit classically). Rutten defines the formal ball $F\langle r, x \rangle$ ($r \in [0, \infty]$, $x \in X$) to be a function from X to $[0, \infty]$, given by $y \mapsto r + X(x, y)$. This is in fact (to use the terminology of [33]) a *right* module over X , in other words a point of $X^{op}\text{-Mod}$. When we consider Rutten's $F\langle r, x \rangle$ with respect to X^{op} we find that it is just our $\mathcal{Y}(x) + r$, where $\mathcal{Y}: X \rightarrow \overline{X}$ is the Yoneda embedding, $\mathcal{Y}(x) = \{B_\varepsilon(y) \mid X(y, x) < \varepsilon\}$. Note that Rutten allows $r = \infty$ here, which does not give a point of $\mathbf{Ball}(X)$ – as a subset of $X \times Q_+$ it is empty. Rutten's ball domain \mathcal{F} over X is defined to be the set of right modules $F\langle r, x \rangle$, so his ball domain over X^{op} (apart from the infinite balls) is included in the set of points of $\mathbf{Ball}(X)$. Once again, our ball domain has the extra generality of allowing the centre to be in the completion of X .

5 Main results

Our strategy now is to show that we have a factorization

$$\begin{array}{ccc} \overline{\mathcal{F}_{\sim} X} & \xrightarrow{i_{\mathcal{F}_{\sim}}} & \mathbf{Ball}(\mathcal{F}_{\sim} X) \\ \downarrow v_{\sim} & & \downarrow \phi'_{\sim} \\ P_{\sim} \overline{X} & \xrightarrow{P_{\sim} i} & P_{\sim} \mathbf{Ball}(X) \end{array}$$

with v_{\sim} in fact a homeomorphism (though ϕ'_{\sim} is not), giving a monad opfunctor $(\mathbf{Comp}, v_{\sim}): (\mathbf{gms}, \mathcal{F}_{\sim}) \rightarrow (\mathbf{Loc}, P_{\sim})$ such that $i: (\mathbf{Comp}, v_{\sim}) \rightarrow (\mathbf{Ball}, \phi'_{\sim})$ is a transformation of monad opfunctors.

There are two main steps in the proof. The first (Section 5.1) is to identify those points of $P_{\sim} \mathbf{Ball}(X)$ that are in the sublocale $P_{\sim} \overline{X}$, and the second (Section 5.2) is to describe the factorization through a homeomorphism. The process will also describe how points of $\overline{\mathcal{F}_{\sim} X}$ (Cauchy filters of balls for $\mathcal{F}_{\sim} X$) satisfy the \square and \diamond opens of $P_{\sim} \mathbf{Ball}(X)$. This will be needed in order to see how they correspond with sublocales of \overline{X} .

5.1 The embeddings $P_{\sim}\bar{X} \hookrightarrow P_{\sim}\text{Ball}(X)$

[3, theorem 22] use their domain theoretic results to deal not only with points of a complete metric space X , but also with compact subspaces. For this they use the Plotkin powerdomain (of which the Vietoris powerlocale is the localic analogue) of their ball domain. They show (their theorem 22) that the compact subspaces of X are in bijection with the rounded ideals I of finite non-empty subsets of $X \times [0, \infty)$ for which

$$\inf_{S \in I} \max_{(x,r) \in S} r = 0.$$

We now give constructive localic analogues of their result, for all three powerlocales and covering the generalized metric case. We shall replace $X \times [0, \infty)$ by $X \times Q_+$ (and drop any assumption that X is complete), and then the results surveyed in Section 2.3 show that the powerlocales of $\text{Ball}(X)$ are got as the ideal completions of $\mathcal{F}(X \times Q_+)$ under suitable orders \supset_{\sim} . Since \bar{X} embeds in $\text{Ball}(X)$, it follows that $P_{\sim}(\bar{X})$ embeds in $\text{Idl}(\mathcal{F}(X \times Q_+), \supset_{\sim})$. Our task in this section is to identify which ideals of $\mathcal{F}(X \times Q_+)$ are in the sublocale $P_{\sim}(\bar{X})$.

[2] also examine powerdomains for generalized metric spaces. Their most detailed working is for the lower. They work in the case where X is complete but has a ‘‘basis’’ B , and the lower powerdomain is then a certain subset of $\widehat{B} = B\text{-Mod}$. In fact (our Proposition 5.1), \widehat{B} can be understood as $P_L \text{Ball}(X)$, so we share a basic approach. However, their characterization of that subset is very different from ours, being described in terms of limits of sequences. They also show (their corollary 7.11) that this subset is isomorphic to the completion of the finite powerset of B with the lower metric. It is difficult to compare this account directly with ours, since they are throughout using not only classical, spatial reasoning, but also sequencewise definitions of completeness and completion ([33] shows that netwise definitions are needed to get a good classical correspondence). They also (their section 7.4) sketch the definition of upper and convex powerdomains, and state without proof that they can be obtained by completing the finite powerset with upper or convex metric.

Before proving the main results of this section, let us give the following result that relates them to the approach of [2].

Proposition 5.1 *Let X be a gms. Then $X\text{-Mod}$ is homeomorphic to $P_L(\text{Ball}(X))$.*

Proof It is straightforward to show that, for any continuous information system D , the rounded downsets of D are equivalent to ideals of $\mathcal{F}_L D$, hence to points of $P_L(\text{Idl}(D))$:

a rounded downset I corresponds to the ideal $J = \{S \mid S \subseteq I\}$, and, inversely, J corresponds to $I = \{s \mid \{s\} \in J\}$.²

Now the points of $X\text{-Mod}$, the rounded upsets of formal open balls, are the rounded downsets with respect to the refinement order \supseteq used in $\text{ball}(X)$, and hence ideals of $\mathcal{F}_L \text{ball}(X)$. We conclude that $X\text{-Mod}$ is homeomorphic to $P_L(\text{Ball}(X))$.

Note that reversing the order on the information system D corresponds to taking the Lawson dual³ of the continuous dcpo, its points being the Scott open filters of points of $\text{Idl}(D)$. \square

We now prove the main results of this section. In each $P_{\sim} \text{Ball}(X) \cong \text{Idl}(\mathcal{F}(X \times Q_+), \supseteq_{\sim})$, we identify which points correspond to those in the image of $P_{\sim} \bar{X}$. Following [3], if $S \in \mathcal{F}(X \times Q_+)$ then we write $rS = \max\{\delta \mid B_{\delta}(x) \in S\} \in \mathbb{Q}$, and if $J \subseteq \mathcal{F}(X \times Q_+)$ then we write $\bar{r}J = \inf\{rS \mid S \in J\} \in [0, \infty]$. In the context of [3] (with X complete and symmetric) they prove that non-empty compact subspaces of X correspond to ideals J of $(\mathcal{F}^+(X \times [0, \infty)), \supseteq_C)$ for which $\bar{r}J = 0$.

We shall strengthen the condition $\bar{r}J = 0$, to one saying that for every $\varepsilon \in Q_+$, every $S \in J$ has a refinement $T \in J$ with $rT < \varepsilon$. For the upper and convex cases (which deal with compact subspaces) this is equivalent to $\bar{r}J = 0$, because if $S \supseteq_U T$ then $rS > rT$. However, in the lower case our condition is stronger.

In proving the theorem, we shall consider the locale embedding $\bar{X} \rightarrow \text{Ball}(X)$ in terms of frame presentations. From the definition of the points as filters of balls, we see immediately that the frame for $\text{Ball}(X)$ can be presented as

$$\begin{aligned} \Omega \text{Ball}(X) &= \text{Fr}\langle B_{\delta}(x) \mid (x \in X, \delta \in Q_+) \mid \\ &\quad B_{\delta}(x) \wedge B_{\delta'}(x') = \bigvee \{B_{\varepsilon}(y) \mid B_{\varepsilon}(y) \subset B_{\delta}(x) \text{ and } B_{\varepsilon}(y) \subset B_{\delta'}(x')\} \\ &\quad (x, x' \in X, \delta, \delta' \in Q_+) \\ \mathbf{true} &= \bigvee \{B_{\delta}(x) \mid x \in X, \delta \in Q_+\} \end{aligned}$$

while the sublocale \bar{X} has the extra relations

$$\mathbf{true} = \bigvee_{x \in X} B_{\varepsilon}(x) \quad (\varepsilon \in Q_+)$$

corresponding to the Cauchy property.

²The equivalence here is essentially that remarked on in [26, after theorem 4.3], using the fact that the rounded downsets of D are the rounded upsets of D^{op} and hence the opens of $\text{Idl}(D^{op})$. Thus $\Omega \text{Idl} D$ is presented, as continuous dcpo, by the information system $\mathcal{F}_L D^{op} \cong (\mathcal{F}_U D)^{op}$. Note that there is a mistake there in [26]. “ $>_U$ ” should be either “ $>_L$ ” or “ $(<_U)^{op}$ ”.

³This is sometimes known as the Hoffmann–Lawson dual, since – according to [7] – it was discovered independently by Hoffmann and by Lawson.

Theorem 5.2 *Let J be a point of $\text{Idl}(\mathcal{F}(X \times Q_+), \supset \sim) \cong P \sim \text{Ball}(X)$. Then J is in the image of $P \sim \bar{X}$ iff for all $S \in J$ and $\varepsilon \in Q_+$, there is some $T \in J$ with $S \supset \sim T$ and $rT < \varepsilon$.*

Proof \sim is L: Let $Y \hookrightarrow Z$ be an arbitrary locale embedding, with ΩY presented over ΩZ by relations $a \leq b$ for $(a, b) \in R \subseteq \Omega Z \times \Omega Z$. By a routine application of the coverage theorem (see [28]), we have

$$\Omega Y \cong \text{SupLat}\langle \Omega Z \text{ (qua SupLat)} \mid a \wedge c \leq b \wedge c \ ((a, b) \in R, c \in \Omega Z) \rangle$$

and it follows that

$$\begin{aligned} \Omega P_L Y &= \text{Fr}\langle \Omega Y \text{ (qua SupLat)} \rangle \\ &\cong \text{Fr}\langle \Omega Z \text{ (qua SupLat)} \mid a \wedge c \leq b \wedge c \ ((a, b) \in R, c \in \Omega Z) \rangle \\ &\cong \text{Fr}\langle \Omega P_L Z \text{ (qua Fr)} \mid \diamond(a \wedge c) \leq \diamond(b \wedge c) \ ((a, b) \in R, c \in \Omega Z) \rangle. \end{aligned}$$

Clearly it suffices to take the opens c just from a base of Z .

In our present case we have $Y = \bar{X}$, $Z = \text{Ball}(X)$, with $\Omega \bar{X}$ presented over $\Omega \text{Ball}(X)$ by relations $\mathbf{true} \leq \bigvee_{y \in X} B_\varepsilon(y)$ ($\varepsilon > 0$). Hence, using the fact that the $B_\delta(x)$'s are a base for $\text{Ball}(X)$, we find that $\Omega P_L \bar{X}$ is presented over $\Omega P_L \text{Ball}(X)$ by relations

$$\begin{aligned} \diamond B_\delta(x) &\leq \bigvee_{y \in X} \diamond(B_\delta(x) \wedge B_\varepsilon(y)) \\ &= \bigvee \{ \diamond B_{\varepsilon'}(y') \mid B_\delta(x) \supset B_{\varepsilon'}(y') \text{ and } \varepsilon' < \varepsilon \}. \end{aligned}$$

We now apply Lemma 2.13 (1). Suppose J satisfies the relations, and suppose $S \in J$ and $\varepsilon \in Q_+$. For each $B_\delta(x) \in S$ we have $\{B_\delta(x)\} \in J$ and so there is some $\{B_{\varepsilon'}(y')\} \in J$ with $B_{\varepsilon'}(y') \subset B_\delta(x)$ and $\varepsilon' < \varepsilon$. Taking those balls $B_{\varepsilon'}(y')$ together, we can find a finite set $T \in J$ such that $S \supset_C T$ – hence $S \supset_L T$ – and $rT < \varepsilon$. The converse is obvious.

\sim is U: This time for the arbitrary locale embedding $Y \hookrightarrow Z$, by a routine application of the *preframe* coverage theorem [12], we have

$$\Omega Y \cong \text{PreFr}\langle \Omega Z \text{ (qua PreFr)} \mid a \vee c \leq b \vee c \ ((a, b) \in R, c \in \Omega Z) \rangle.$$

It follows that

$$\begin{aligned} \Omega P_U Y &= \text{Fr}\langle \Omega Y \text{ (qua PreFr)} \rangle \\ &\cong \text{Fr}\langle \Omega Z \text{ (qua PreFr)} \mid a \vee c \leq b \vee c \ ((a, b) \in R, c \in \Omega Z) \rangle \\ &\cong \text{Fr}\langle \Omega P_U Z \text{ (qua Fr)} \mid \square(a \vee c) \leq \square(b \vee c) \ ((a, b) \in R, c \in \Omega Z) \rangle. \end{aligned}$$

In our present case with relations $\mathbf{true} \leq \bigvee_y B_\varepsilon(y)$ ($\varepsilon > 0$), the opens c appearing above make no difference ($\mathbf{true} \vee c = \mathbf{true}$). Hence we find that $\Omega P_U \bar{X}$ is presented over $\Omega P_U \text{Ball}(X)$ by relations

$$\mathbf{true} \leq \square \bigvee_{y \in X} B_\varepsilon(y) = \bigvee^{\uparrow} \{ \square \bigvee_{y \in T'} B_\varepsilon(y) \mid T' \in \mathcal{FX} \}.$$

We now apply Lemma 2.13 (2). Suppose J satisfies the relations, and suppose $S \in J$ and $\varepsilon \in Q_+$. From the relations we can find $T' \in \mathcal{FX}$ such that $\{B_\varepsilon(y) \mid y \in T'\} \in J$. Let $T \in J$ be such that $S \supset_U T$ and $\{B_\varepsilon(y) \mid y \in T'\} \supset_U T$. Then $rT < \varepsilon$ and T is as required. Conversely, suppose the condition holds. Let $\varepsilon \in Q_+$. We can find $S \in J$ (which is inhabited), and so there is some $T \in J$ with $S \supset_U T$ and $rT < \varepsilon$. If $T' = \{y \mid \exists \alpha. B_\alpha(y) \in T\}$ then $\{B_\varepsilon(y) \mid y \in T'\} \in J$ as required.

\sim is C: This time for an arbitrary locale embedding $Y \hookrightarrow Z$, combining the calculations for the lower and upper cases, we get

$$\begin{aligned} \Omega VY &= \text{Fr}\langle \Omega Y \text{ (qua SupLat)}, \Omega Y \text{ (qua PreFr)} \mid \\ &\quad \square d \wedge \diamond e \leq \diamond(d \wedge e), \\ &\quad \square(d \vee e) \leq \square d \vee \diamond e \rangle \\ &\cong \text{Fr}\langle \Omega VZ \text{ (qua Fr)} \mid \diamond(a \wedge c) \leq \diamond(b \wedge c), \square(a \vee c) \leq \square(b \vee c) \\ &\quad ((a, b) \in R, c \in \Omega Z) \rangle. \end{aligned}$$

In our present case, as before, these relations reduce to

$$\begin{aligned} \diamond B_\delta(x) &\leq \bigvee \{ \diamond B_{\varepsilon'}(y') \mid B_\delta(x) \supset B_{\varepsilon'}(y') \text{ and } \varepsilon' < \varepsilon \} \\ \mathbf{true} &\leq \bigvee^{\uparrow} \{ \square \bigvee_{y \in T'} B_\varepsilon(y) \mid T' \in \mathcal{FX} \}. \end{aligned}$$

However, given the second, we have the first (in fact they are equivalent): for

$$\begin{aligned} \diamond B_\delta(x) &\leq \bigvee^{\uparrow} \{ \diamond B_\delta(x) \wedge \square \bigvee_{y \in T'} B_\varepsilon(y) \mid T' \in \mathcal{FX} \} \\ &\leq \bigvee^{\uparrow} \{ \diamond(B_\delta(x) \wedge \bigvee_{y \in T'} B_\varepsilon(y)) \mid T' \in \mathcal{FX} \} \\ &= \bigvee_{y \in X} \diamond(B_\delta(x) \wedge B_\varepsilon(y)) \leq \text{RHS of first.} \end{aligned}$$

From Lemma 2.13 we see that J satisfies $\square \bigvee \{B_\varepsilon(y) \mid B_\varepsilon(y) \in U\}$ iff $U \supset_U V$ for some $V \in J$, and then $U' \supset_C V$ for some finite $U' \subseteq U$.

Suppose J satisfies the relations, and $S \in J$ and $\varepsilon \in Q_+$. From the relations, find $U \in \mathcal{F}X$ and $V \in J$ such that $\{B_\varepsilon(x) \mid x \in U\} \supset_U V$, and then $U' \subseteq U$ such that $\{B_\varepsilon(x) \mid x \in U'\} \supset_C V$ and hence $\{B_\varepsilon(x) \mid x \in U'\} \in J$. If T is an upper bound for S and $\{B_\varepsilon(x) \mid x \in U'\}$ in J , then $rT < \varepsilon$ as required. The converse argument is essentially the same as for the upper powerlocale. \square

Notice that although the statement of the Theorem is geometric, its proof is not – it uses frames, suplattices and preframes, which are not geometric structures. However, the proof is topos-valid and so holds at every stage of definition. Implicitly, it also uses the fact that the powerlocale constructions themselves are geometric [32] in order to ensure that Theorem 5.2 applies also to generalized points.

We refine the Theorem slightly to show that T can be chosen of the form $\phi(B_\beta(T'))$ (with ϕ as in Definition 4.4).

Lemma 5.3 *Let X be a gms, let \sim stand for L, U or C, and suppose J is an ideal of $(\mathcal{F}X \times Q_+, \supset_\sim)$. If J satisfies the condition of Theorem 5.2, namely that for every $S \in J$ and $\varepsilon \in Q_+$ there is some $T \in J$ with $S \supset_\sim T$ and $rT < \varepsilon$, then for every $S \in J$ and $\varepsilon \in Q_+$ there is some $\phi(B_\beta(T')) \in J$ with $S \supset_\sim \phi(B_\beta(T'))$ and $\beta < \varepsilon$.*

Proof We can find $\delta \in Q_+$ such that $S' = \{B_{\alpha-\delta}(x) \mid B_\alpha(x) \in S\} \in J$, and then we can find $T \in J$ such that $S' \supset_\sim T$ and $rT < \min(\delta, \varepsilon)$. Choose $\beta \in Q_+$ such that $rT < \beta < \min(\delta, \varepsilon)$, and let $T' = \{y \mid \exists \gamma. B_\gamma(y) \in T\}$. Then $\phi(B_\beta(T')) \supset_C T$, so $\phi(B_\beta(T')) \in J$. Also, $S \supset_\sim \phi(B_\beta(T'))$. To see this when \sim is L, if $B_\alpha(x) \in S$ then we have $B_{\alpha-\delta}(x) \supset B_\gamma(y) \in T$, and then $B_\alpha(x) \supset B_\beta(y) \in \phi(B_\beta(T'))$, because $\beta - \gamma < \beta < \delta$. The argument when \sim is U is similar, and then the case for C follows. \square

5.2 Powerlocales of localic completions

We shall be working with the following diagram. ϕ_\sim, ϕ'_\sim and the homeomorphism v'_\sim are Definitions 4.4, 4.7 and 2.12; v_\sim is the homeomorphism we are constructing.

$$\begin{array}{ccc}
 \overline{\mathcal{F}_\sim X} \xrightarrow{i_{\mathcal{F}_\sim}} \mathbf{Ball}(\mathcal{F}_\sim X) = \mathbf{Idl}(\mathbf{ball}(\mathcal{F}_\sim X)) & \xrightarrow{\mathbf{Idl} \phi_\sim} & \mathbf{Idl}(\mathcal{F}_\sim(\mathbf{ball}(X))) \\
 \downarrow v_\sim & & \downarrow \phi'_\sim \\
 P_\sim \overline{X} \xrightarrow{P_\sim i} P_\sim \mathbf{Ball}(X) = P_\sim \mathbf{Idl}(\mathbf{ball}(X)) & & \swarrow v'_\sim \text{ ball}
 \end{array}$$

Theorem 5.4 *Let X be a gms, and let \sim stand for L, U or C. Then ϕ'_\sim factors through a homeomorphism $v_\sim: \overline{\mathcal{F}_\sim X} \cong P_\sim \overline{X}$, giving a monad opfunctor $(\text{Comp}, v_\sim): (\text{gms}, \mathcal{F}_\sim) \rightarrow (\text{Loc}, P_\sim)$ and $i: (\text{Comp}, v_\sim) \rightarrow (\text{Ball}, \phi'_\sim)$ a transformation of monad opfunctors.*

Proof Let I be an ideal of $(\mathcal{F}_\sim X \times Q_+, \supset)$. We show that if I is Cauchy, then $\text{Idl}(\phi_\sim)(I) = (\supset_\sim \phi(I))$ satisfies the condition of Theorem 5.2. Suppose $S \supset_\sim \phi(B_\alpha(S'))$ with $B_\alpha(S') \in I$, and $\varepsilon \in Q_+$. We can find $B_\alpha(S') \supset B_\beta(T') \in I$ with $\beta < \varepsilon$, and then, using Lemma 4.5, $S \supset_\sim \phi(B_\beta(T')) \in \text{Idl}(\phi_\sim)(I)$, with $r(\phi(B_\beta(T'))) \leq \beta < \varepsilon$. (We have only \leq , because in some situations T' might be empty.) Hence $\text{Idl}(\phi_\sim)$ restricts to $v_\sim: \overline{\mathcal{F}_\sim X} \rightarrow P_\sim \overline{X}$.

At this point we see by Lemma 2.7 that (Comp, v_\sim) is a monad opfunctor and $i: (\text{Comp}, v_\sim) \rightarrow (\text{Ball}, \phi'_\sim)$ is a transformation of monad opfunctors. Note that each P_\sim preserves embeddings. (In fact this follows from the proof of Theorem 5.2.)

We also have $I = \phi^{-1}(\text{Idl}(\phi_\sim)(I))$. For suppose $\phi(B_\delta(S)) \supset_\sim \phi(B_\varepsilon(T))$ with $B_\varepsilon(T) \in I$. By the Cauchy property we can assume $\varepsilon < \delta$, and then by Lemma 4.5 we have $B_\delta(S) \supset B_\varepsilon(T)$ so $B_\delta(S) \in I$.

Now suppose J is an ideal of $(\mathcal{F}(X \times Q_+), \supset_\sim)$ satisfying the condition of Theorem 5.2. We show that $\phi^{-1}(J)$ is an ideal of $(\mathcal{F}_\sim X \times Q_+, \supset)$ and that it is Cauchy. Clearly $\phi^{-1}(J) = (\supset \phi^{-1}(J))$. For the rest suppose $B_{\alpha_i}(S'_i) \in \phi^{-1}(J)$ ($i = 1, 2$) and $\varepsilon \in Q_+$. Then the $\phi(B_{\alpha_i}(S'_i))$ s have an upper bound in the ideal J and using Lemma 5.3 there is some $\phi(B_\beta(T')) \in J$ such that $\phi(B_{\alpha_i}(S'_i)) \supset_\sim \phi(B_\beta(T'))$ and $\beta < \min(\alpha_1, \alpha_2, \varepsilon)$. Using Lemma 4.5 we see that $B_\beta(T')$ refines both $B_{\alpha_i}(S'_i)$ s in $\phi^{-1}(J)$ with $\beta < \varepsilon$, so $\phi^{-1}(J)$ is both an ideal and Cauchy. From Lemma 5.3 we also deduce $J = (\supset_\sim \phi(\phi^{-1}(J)))$. \square

It is straightforward to check that these homeomorphisms restrict to the positive parts, giving $\overline{\mathcal{F}_\sim^+ X} \cong P_\sim^+ \overline{X}$.

Having identified $P_\sim \overline{X}$ with $\overline{\mathcal{F}_\sim X}$, we should ask when points of $\overline{\mathcal{F}_\sim X}$ are in the \square and \diamond opens.

Proposition 5.5 *Let B be a finite subset of $X \times Q_+$.*

- (1) *If I is a Cauchy filter for $\mathcal{F}_\sim X$ (\sim standing for L or C), then $v_\sim(I)$ is in $\bigwedge \{\diamond B_\delta(x) \mid (x, \delta) \in B\}$ iff there is some $B_\varepsilon(S) \in I$ such that $B \supset_L \phi(B_\varepsilon(S))$.*
- (2) *If I is a Cauchy filter for $\mathcal{F}_\sim X$ (\sim standing for U or C), then $v_\sim(I)$ is in $\square(\bigvee B) = \square \bigvee \{B_\delta(x) \mid (x, \delta) \in B\}$ iff there is some $B_\varepsilon(S) \in I$ such that $B \supset_U \phi(B_\varepsilon(S))$.*

Proof In each case we consider I as a point of $\text{Ball}(\mathcal{F}_\sim X)$, and ask when $\phi'_\sim(I)$ is in the corresponding open of $P_\sim(\text{Ball}(X))$. The answer can be derived from Lemma 2.13.

(1): $\phi'_\sim(I)$ is in $\bigwedge\{\diamond B_\delta(x) \mid (x, \delta) \in B\}$ iff $B \in (\supset_L \phi'_\sim(I)) = (\supset_L (\supset_\sim \phi(I))) = (\supset_L \phi(I))$ where $\phi(I)$ denotes the direct image.

(2) is similar. \square

Proposition 5.6 *Let I be a Cauchy filter for $\mathcal{F}_C X$. Then $B_\delta(S) \in I$ iff $v_\sim(I)$ is in both $\square(\bigvee_{x \in S} B_\delta(x))$ and $\bigwedge_{x \in S} \diamond B_\delta(x)$.*

Proof \Rightarrow is clear. For \Leftarrow , and using Proposition 5.5, suppose $\phi(B_\delta(S)) \supset_U \phi(B_\alpha(A))$ and $\phi(B_\delta(S)) \supset_L \phi(B_\beta(B))$ with $B_\alpha(A), B_\beta(B) \in I$. Choose $B_\varepsilon(T) \in I$ such that $B_\alpha(A) \supset B_\varepsilon(T)$ and $B_\beta(B) \supset B_\varepsilon(T)$ in $\mathcal{F}_C X$, and $\varepsilon < \delta$. Using Lemma 4.5 we have $\phi(B_\delta(S)) \supset_\sim \phi(B_\varepsilon(T))$ with \sim standing for U or L, and hence also for C. Then again by Lemma 4.5 we have $B_\delta(S) \supset B_\varepsilon(T)$ in $\mathcal{F}_C X$, so $B_\delta(S) \in I$. \square

We complete this section with an analysis of the maps \Downarrow and \Uparrow .

Proposition 5.7 *For any gms X , the identity function on $\mathcal{F}X$ gives non-expansive maps $\mathcal{F}_C X \rightarrow \mathcal{F}_L X$ and $\mathcal{F}_C X \rightarrow \mathcal{F}_U X$. These lift to the maps $\Downarrow: P_C \bar{X} \rightarrow P_L \bar{X}$ and $\Uparrow: P_C \bar{X} \rightarrow P_U \bar{X}$.*

Proof We find monad opfunctors

$$(\mathbf{gms}, \text{Id}_\sim): (\mathbf{gms}, \mathcal{F}_C) \rightarrow (\mathbf{gms}, \mathcal{F}_\sim),$$

$$(\mathbf{cis}, \text{Id}_\sim): (\mathbf{cis}, \mathcal{F}_C) \rightarrow (\mathbf{cis}, \mathcal{F}_\sim) \text{ and}$$

$$(\mathbf{Loc}, I_\sim): (\mathbf{Loc}, P_C) \rightarrow (\mathbf{Loc}, P_\sim)$$

where Id_\sim in each case is just the identity on the finite powerset, and $I_\sim: P_C \rightarrow P_\sim$ is \Uparrow, \Downarrow or Id according as \sim is U, L or C.

In the following diagram of monad opfunctors, the two squares commute.

$$\begin{array}{ccccc} (\mathbf{gms}, \mathcal{F}_C) & \xrightarrow{(\text{ball}, \phi_C)} & (\mathbf{cis}, \mathcal{F}_C) & \xrightarrow{(\text{Idl}, v'_C)} & (\mathbf{Loc}, P_C) \\ (\mathbf{gms}, \text{Id}_\sim) \downarrow & & (\mathbf{cis}, \text{Id}_\sim) \downarrow & & \downarrow (\mathbf{Loc}, I_\sim) \\ (\mathbf{gms}, \mathcal{F}_\sim) & \xrightarrow{(\text{ball}, \phi_\sim)} & (\mathbf{cis}, \mathcal{F}_\sim) & \xrightarrow{(\text{Idl}, v'_\sim)} & (\mathbf{Loc}, P_\sim) \end{array}$$

For the left hand square this is elementary, while the right hand can be checked (by considering inverse image functions) using Definition 2.12 – essentially it is because the same definitions work in the different powerlocales.

These two squares together give a monad opfunctor $(\mathbf{Ball}, \psi_{\sim}) : (\mathbf{gms}, \mathcal{F}_C) \rightarrow (\mathbf{Loc}, P_{\sim})$. We have monad opfunctor transformations

$$\begin{aligned} i(\mathbf{gms}, \text{Id}_{\sim}) : (\mathbf{Comp}, v_{\sim})(\mathbf{gms}, \text{Id}_{\sim}) &\rightarrow (\mathbf{Ball}, \psi_{\sim}) \text{ and} \\ (\mathbf{Loc}, I_{\sim})i : (\mathbf{Loc}, I_{\sim})(\mathbf{Comp}, v_C) &\rightarrow (\mathbf{Ball}, \psi_{\sim}). \end{aligned}$$

The identity natural transformation on \mathbf{Comp} makes a commutative triangle with these at the level of natural transformations, and we can apply Lemma 2.8 to see that it is a monad opfunctor transformation from $(\mathbf{Loc}, I_{\sim})(\mathbf{Comp}, v_C)$ to $(\mathbf{Comp}, v_{\sim})(\mathbf{gms}, \text{Id}_{\sim})$. The effect of this is to show that \uparrow and \downarrow are the lifted maps. \square

6 Compactness and overtness

For our first applications we look at two important properties of locales that can be easily addressed using powerlocales.

6.1 Compactness

A well known classical property of complete metric spaces X is that they are compact iff *totally bounded*: for every $\varepsilon > 0$ there is a *finite* $S \subseteq X$ such that the open ε -balls centred on elements of S cover X . (Given a dense subspace D , one can even choose $S \subseteq D$.) Constructively, [1] used total boundedness as the *definition* of compactness for complete metric spaces; [18] shows that this is constructively equivalent to compactness of a corresponding localic completion in the style of [33].

We now use powerlocale methods to show this result quite generally for localic completions: a gms completion \bar{X} is compact iff X is totally bounded. (More information on totally bounded quasimetric spaces can be found in [22].) We shall apply a basic result that a locale is compact iff its upper powerlocale has a least point in the following strong sense. We say that a locale X is *local* if the unique map $! : X \rightarrow 1$ has a left adjoint, a global point $\perp : 1 \rightarrow X$ such that $\perp \circ ! \sqsubseteq \text{Id}_X$. This can be expressed by saying that \perp is less than the generic point, in other words that \perp is less than all generalized points. Hence \perp is a bottom point of X in a strong sense. (This is a special case of the concept of *local topos*, which has been studied in [11]; see [10].) To prove that a locale is local, we shall normally give a geometric definition of the bottom point and show that it is less than every point. The geometricity allows us to deduce that the bottom point is less than the *generic* point.

Theorem 6.1 [27]

A locale Y is compact iff $P_U Y$ is local. Its bottom point then corresponds to Y as a sublocale of itself.

The usual definition of total boundedness is that for every $\delta > 0$ there is a finite subset $S \subseteq X$ that is a δ -cover in the sense that for every $x \in X$ there is some $s \in S$ with $X(s, x) < \delta$. The universal quantification here ($\forall x \in X$) is intuitionistic but not geometric, so we give a geometric definition in which the relationship between δ and S is given as a relation Cov in the theory. Hence total boundedness is not (geometrically) a *property* of a gms but additional *structure*. We shall, however, present it in such a way that it is unique when it exists.

Definition 6.2 A *totally bounded gms* X is one equipped with a relation $\text{Cov} \subseteq \mathcal{F}X \times Q_+$ satisfying the following axioms:

- (TB1) $\forall S \in \mathcal{F}X. \forall \delta \in Q_+. \forall x \in X. (\text{Cov}(S, \delta) \rightarrow \exists s \in S. X(s, x) < \delta)$
- (TB2) $\forall \delta \in Q_+. \exists S \in \mathcal{F}X. \text{Cov}(S, \delta)$
- (TB3) $\forall S \in \mathcal{F}X. \forall \delta \in Q_+. (\text{Cov}(S, \delta) \rightarrow \exists \delta' \in Q_+. (\delta' < \delta \wedge \text{Cov}(S, \delta')))$
- (TB4) $\forall S, T \in \mathcal{F}X. \forall \delta, \varepsilon \in Q_+. (\text{Cov}(T, \varepsilon) \wedge \mathcal{F}_U X(S, T) < \delta$
 $\rightarrow \text{Cov}(S, \delta + \varepsilon))$

Note that from **TB1** we can deduce that if $\text{Cov}(S, \delta)$ then $\mathcal{F}_U X(S, T) < \delta$ for every $T \in \mathcal{F}X$.

Note also that if Cov is viewed (in the obvious way) as a set of formal open balls for $\mathcal{F}_U X$, then conditions **TB2**, **TB3** and **TB4** are equivalent to saying that Cov is a rounded upper set containing balls of arbitrarily small radius (the Cauchy property).

Proposition 6.3 Let X be a *totally bounded gms*. Then $\text{Cov}(S, \delta)$ iff $\exists \delta' < \delta$ such that S is a δ' -cover (ie $\forall x \in X. \exists s \in S. X(s, x) < \delta'$).

Proof \Rightarrow : Combine **TB3** with **TB1**.

\Leftarrow : By **TB2**, we can find T with $\text{Cov}(T, \delta - \delta')$, and by hypothesis $\mathcal{F}_U X(S, T) < \delta'$. Then $\text{Cov}(S, \delta)$ by **TB4**. \square

It follows that on any given gms X , if Cov can be defined at all then it is unique.

The axiomatization is strong in order to characterize Cov uniquely. However, it is useful to know that we can get by with weaker structure.

Proposition 6.4 *Let X be a gms and let $\text{Cov}_0 \subseteq \mathcal{F}X \times \mathcal{Q}_+$ be such that axioms **TB1** and **TB2** hold when Cov_0 is substituted for Cov . Then X can be given the structure of total boundedness.*

Proof Define $\text{Cov}(S, \delta)$ if for some $\delta' < \delta$ and some T we have $\mathcal{F}_U X(S, T) < \delta'$ and $\text{Cov}_0(T, \delta - \delta')$. We prove the four axioms.

TB1: Suppose $\text{Cov}(S, \delta)$ with T and δ' as above, and suppose $x \in X$. There is some $t \in T$ with $X(t, x) < \delta - \delta'$, and then some $s \in S$ with $X(s, t) < \delta'$. Then $X(s, x) < \delta$.

TB2: Choose T with $\text{Cov}_0(T, \delta/2)$. We have $\mathcal{F}_U X(T, T) = 0 < \delta/2$, and it follows that $\text{Cov}(T, \delta)$.

TB3: Given $\text{Cov}(S, \delta)$, in the part of the definition that says $\mathcal{F}_U X(S, T) < \delta'$ we can reduce δ' to some δ'' and thereby reduce δ to $\delta - (\delta' - \delta'')$.

TB4: Given the hypotheses of **TB4**, we have some $\varepsilon' < \varepsilon$ and U such that $\text{Cov}_0(U, \varepsilon - \varepsilon')$ and $\mathcal{F}_U X(T, U) < \varepsilon'$. Then $\mathcal{F}_U X(S, U) < \delta + \varepsilon'$, so $\text{Cov}(S, \delta + \varepsilon)$. \square

Lemma 6.5 *Let X be a totally bounded gms. Then $\overline{\mathcal{F}_U X}$ is local, with Cov (as a set of formal balls) its least point.*

Proof We have already noted that Cov is upper and Cauchy. For binary filteredness, suppose $\text{Cov}(S_i, \delta_i)$ ($i = 1, 2$). By **TB3** we can find $\delta'_i < \delta_i$ and $\text{Cov}(S_i, \delta'_i)$. Let $\varepsilon = \min_i(\delta_i - \delta'_i)$ and choose T with $\text{Cov}(T, \varepsilon)$. Then it follows that $\mathcal{F}_U X(S_i, T) + \varepsilon < \delta_i$, which is what was needed.

Now let F be any point of $\overline{\mathcal{F}_U X}$. We want to show $\text{Cov} \subseteq F$. Suppose $\text{Cov}(S, \delta)$, and find $\delta' < \delta$ such that $\text{Cov}(S, \delta')$. By the Cauchy property for F , there is some T with $B_{\delta - \delta'}(T) \in F$. Then $\mathcal{F}_U X(S, T) < \delta'$ and so $B_{\delta - \delta'}(T) \subset B_\delta(S)$ and $B_\delta(S) \in F$. \square

There is a logical subtlety here, relying on the geometric constructivism of the argument. When we let F be “any” point of $\overline{\mathcal{F}_U X}$, we allow arbitrary generalized points, not just global points. To explain it in terms of categorical logic, we can use the argument internally in sheaves over $\overline{\mathcal{F}_U X}$ to show that Cov is less than the generic point of $\overline{\mathcal{F}_U X}$. In other words, the map $!; \text{Cov}: \overline{\mathcal{F}_U X} \rightarrow 1 \rightarrow \overline{\mathcal{F}_U X}$ is less (in the specialization order) than the identity map on $\overline{\mathcal{F}_U X}$, which was the definition of locality. This is stronger than saying that Cov is less than all global points. A more concrete argument can be found by analysing the above proof to find the inverse image function $(!; \text{Cov})^*$.

Lemma 6.6 *Let X be a gms and suppose $\overline{\mathcal{F}_U X}$ is local. Then X is totally bounded.*

Proof Let K be the least point of $\overline{\mathcal{F}_U X}$. We define $\text{Cov}(S, \delta)$ if $B_\delta(S) \in K$. Axioms **TB2**, **TB3** and **TB4** follow easily from the fact that K is a Cauchy filter. To prove **TB1**, suppose $B_\delta(S) \in K$ and we are given $x \in X$. Consider the Cauchy filter $\mathcal{Y}(x) = \{B_\varepsilon(y) \mid X(y, x) < \varepsilon\}$. The corresponding point $\uparrow \mathcal{Y}(x)$ of $P_U \overline{X} \cong \overline{\mathcal{F}_U X}$ is $\{B_\varepsilon(T) \mid \mathcal{F}_U X(T, \{x\}) < \varepsilon\}$. We have $K \sqsubseteq \uparrow \mathcal{Y}(x)$, and it follows that $\mathcal{F}_U X(S, \{x\}) < \delta$. Hence there is some $s \in S$ with $X(s, x) < \delta$. \square

Theorem 6.7 *Let X be a gms. Then \overline{X} is compact iff X is totally bounded.*

Proof Combine Theorem 6.1 with Lemmas 6.5 and 6.6. \square

6.2 Overtness

“Overt” here is Paul Taylor’s synonym of “open” [13], in the sense that a locale Y is overt if the unique map $! : Y \rightarrow 1$ is an open map. This means that for every open U in Y , its image under $!$ is open in 1 and hence is a proposition $\text{Pos}(U)$. Thus Pos is a “positivity predicate”. Actually, the positivity predicate can always be defined, by $\text{Pos}(U)$ holding if every open cover of U is inhabited. However [8], overtness implies in addition that every open is a join of positive opens.

Classically, overtness is not an issue since every locale is overt, with U positive iff $U \neq \emptyset$. Constructively it becomes important, and in many ways is a counterpart of compactness. In formal topology, it is often taken as part of the basic definition. (See [17] for a discussion of the relationship between localic overtness and the positivity predicate in formal topology.)

We now use powerlocale methods to provide a simple proof that all gms completions are overt. Dual to localness, a locale X is *colocal* iff the unique map $!$ has a right adjoint $\top : 1 \rightarrow X$ (a top point). (This is a special case of the concept of *totally connected topos* [10, C 3.6.16].)

Theorem 6.8 [27]

A locale Y is overt iff $P_L Y$ is colocal. Its top point then corresponds to Y as a sublocale of itself.

Corollary 6.9 *If X is a gms then \overline{X} is overt.*

Proof If $\delta > \varepsilon$ then in $\mathcal{F}_L X$ we have $B_\delta(S) \supset B_\varepsilon(S \cup T)$ for all S and T , so any two balls $B_{\delta_i}(S_i)$ ($i = 1, 2$) have a common refinement $B_\varepsilon(S_1 \cup S_2)$ where $\varepsilon < \min(\delta_1, \delta_2)$. It follows that $\mathcal{F}X \times Q_+$ is a point of $\overline{\mathcal{F}_L X}$, and hence must be the top point. We can now apply Theorem 6.8. \square

7 Sublocales of \mathbb{R}

We now look at some applications to those sublocales of the reals $\mathbb{R} \cong \overline{\mathbb{Q}}$ that can be expressed as powerlocale points. Theorem 5.4 offers us the opportunity of defining powerlocale points as Cauchy filters of formal balls, and this gives access to geometric techniques for reasoning with the corresponding sublocales of the reals. The working is reduced to elementary manipulations of the rationals and finite sets of them, and ends up describing subspaces not by their points, but by the opens that contain or meet them. A good example of the style is [38], which deals with connectedness in the reals, with applications to the Intermediate Value Theorem. In fact, as is explained in section 7.1 there, this unfamiliar style of reasoning still makes sense in classical topology.⁴

Since \mathbb{R} is regular, all its sublocales are fitted, and its compact sublocales are closed and hence weakly closed. Thus its powerlocale points can be described as follows.

- In $P_L\mathbb{R}$: overt, weakly closed sublocales.
- In $P_U\mathbb{R}$: compact sublocales.
- In $V\mathbb{R}$: compact, overt sublocales.

Classically all locales are overt, and weakly closed is equivalent to closed, so it might seem that there is little to choose between the powerlocales. In particular both $P_U\mathbb{R}$ and $V\mathbb{R}$ have as their classical points the compact sublocales of \mathbb{R} . However, $V\mathbb{R}$ has a finer topology (with opens $\diamond U$ as well as $\square U$). Constructively, the requirement for overtness needs extra information on the points. In effect, a compact sublocale is approximated “from above” (the opens $\square U$ provide information about what includes the sublocale), while an overt sublocale is approximated “from below” (the opens $\diamond U$ provide information about what is in the sublocale). This becomes important in Section 7.1, where we see how to calculate the inf and sup of points of $V^+\mathbb{R}$. To approximate sup K from above or below we need approximations of K from above or below respectively (and inf K is similar but the other way round).

7.1 Bounds of Vietoris points

In this section we examine the maps sup and inf from $V^+\mathbb{R}$ to \mathbb{R} . (We have to use $V^+\mathbb{R}$ rather than $V\mathbb{R}$, because the sup and inf of the empty set would have to be infinite.) These can be defined as lifts of gms homomorphisms.

⁴Another approach to such questions is Taylor’s study [24] in the context of his Abstract Stone Duality. Again, subspaces are described in terms of the opens that contain or meet them.

Proposition 7.1 *The functions \max and $\min: \mathcal{F}_C^+ \mathbb{Q} \rightarrow \mathbb{Q}$ are non-expansive.*

Proof We prove the result for \max . For \min it is dual, by order reversal on \mathbb{Q} .

Let S and T be in $\mathcal{F}^+ \mathbb{Q}$, let $s_{\max} = \max(S)$, $t_{\max} = \max(T)$, and let $q = \mathcal{F}_C^+ \mathbb{Q}(S, T)$, a non-negative rational. Since $t_{\max} \in T$ we have that t_{\max} is within q of some $s \in S$ and then $t_{\max} \leq s + q \leq s_{\max} + q$. Similarly, $s_{\max} \leq t_{\max} + q$ and so $|t_{\max} - s_{\max}| \leq q$. \square

Definition 7.2 We define $\sup: V^+ \mathbb{R} \rightarrow \mathbb{R}$ as $\overline{\max}: V^+ \mathbb{R} \cong \overline{\mathcal{F}_C^+ \mathbb{Q}} \rightarrow \overline{\mathbb{Q}} \cong \mathbb{R}$. Similarly, \inf is $\overline{\min}$.

Our goal now is to show how, if K is a point of $V^+ \mathbb{R}$, $\sup(K)$ genuinely is the supremum of K . (We focus on \sup from now on; the results for \inf are entirely dual.) We show in fact that it is the greatest element of K : $\sup(K) \in K$, and if $x \in K$ (see Theorem 2.3) then $x \leq \sup(K)$.

Lemma 7.3 *If K is a point of $V^+ \mathbb{R}$, then $\sup(K) \in K$.*

Proof We must show $\downarrow \sup(K) \sqsubseteq \downarrow K$ and $\uparrow \sup(K) \supseteq \uparrow K$. Now $\sup, \downarrow: V^+ \mathbb{R} \rightarrow \mathbb{R} \rightarrow P_L \mathbb{R}$ lifts $\max; \{-\}: \mathcal{F}_C^+ \mathbb{Q} \rightarrow \mathbb{Q} \rightarrow \mathcal{F}_L \mathbb{Q}$ and by Proposition 5.7 $\downarrow: V^+ \mathbb{R} \rightarrow P_L \mathbb{R}$ lifts $\text{Id}: \mathcal{F}_C^+ \mathbb{Q} \rightarrow \mathcal{F}_L \mathbb{Q}$. Hence to prove $\downarrow \circ \sup \sqsubseteq \downarrow$ it suffices by Proposition 2.21 to show that $\mathcal{F}_L \mathbb{Q}(\{\max(S)\}, S) = 0$ for every $S \in \mathcal{F}^+ \mathbb{Q}$. This is obvious, because $\max(S) \in S$. The other half, $\uparrow \circ \sup \supseteq \uparrow$, is dual. \square

Lemma 7.4 *If x is a point of \mathbb{R} then $\sup(\{x\}) = x$.*

Proof $\{-\}; \sup: \mathbb{R} \rightarrow V^+ \mathbb{R} \rightarrow \mathbb{R}$ lifts $\{-\}; \max: \mathbb{Q} \rightarrow \mathcal{F}_C^+ \mathbb{Q} \rightarrow \mathbb{Q}$, which is the identity. \square

We now proceed to show that if $K \subseteq L$ are points of $V^+ \mathbb{R}$, then $\sup(K) \leq \sup(L)$. Note that by $K \subseteq L$ we mean the order corresponding to that of the sublocales: $\uparrow K \supseteq \uparrow L$ and $\downarrow K \sqsubseteq \downarrow L$.

We first investigate a locale that will be useful.

Definition 7.5 Let $\overrightarrow{\mathbb{Q}}$ be the gms whose elements are the rationals, but whose metric is defined as truncated minus,

$$\overrightarrow{\mathbb{Q}}(x, y) = x \dot{-} y = \max(0, x - y).$$

It is shown in [33] that $\overrightarrow{\mathbb{Q}}$ is homeomorphic to the ideal completion of $(\mathbb{Q}, <)$, in other words its points are equivalent to rounded lower inhabited subsets of \mathbb{Q} . It is the locale $\overrightarrow{(-\infty, \infty]}$ of *lower reals*.

Lemma 7.6 In $\overrightarrow{\mathbb{Q}}$ we have $B_\varepsilon(y) \subset B_\delta(x)$ iff $\varepsilon < \delta$ and $x - \delta < y - \varepsilon$.

Proof

$$\begin{aligned} B_\varepsilon(y) \subset B_\delta(x) &\Leftrightarrow (x \dot{-} y) < \delta - \varepsilon \\ &\Leftrightarrow 0 < \delta - \varepsilon \text{ and } x - y < \delta - \varepsilon \end{aligned}$$

□

Lemma 7.7 $\text{Id}: \mathbb{Q} \rightarrow \overrightarrow{\mathbb{Q}}$ lifts to the map $\downarrow: \mathbb{R} \rightarrow \overrightarrow{(-\infty, \infty]}$ that takes each Dedekind section (L, R) to L .

Proof It is shown in [33] that (L, R) as a Cauchy filter is

$$\{B_\delta(x) \mid x - \delta \in L, x + \delta \in R\}.$$

This maps to

$$\{B_\varepsilon(y) \mid \exists x, \delta. (x - \delta \in L \text{ and } x + \delta \in R \text{ and } \delta < \varepsilon \text{ and } y - \varepsilon < x - \delta)\}$$

and this in turn corresponds, as an ideal of $(\mathbb{Q}, <)$, to

$$\{y - \varepsilon \mid \exists x, \delta. (x - \delta \in L \text{ and } x + \delta \in R \text{ and } \delta < \varepsilon \text{ and } y - \varepsilon < x - \delta)\}.$$

But this is just L again. To show that it contains L , suppose $z \in L$, and by roundedness find $z < z' \in L$. Now find $w \in R$ and let $x = (z' + w)/2$, $\delta = (w - z')/2 = x - z'$. Then $x - \delta = z' \in L$ and $x + \delta = w \in R$. Let $y = x$, $\varepsilon = y - z > \delta$. Then $y - \varepsilon = z < z' = x - \delta$. □

Lemma 7.8 If $K \subseteq L$ are points of $V^+\mathbb{R}$, then $\text{sup}(K) \leq \text{sup}(L)$.

Proof The function $\text{max}: \mathcal{F}_L^+\mathbb{Q} \rightarrow \overrightarrow{\mathbb{Q}}$ is non-expansive. Let $S, T \in \mathcal{F}^+\mathbb{Q}$, $s_{\text{max}} = \text{max}(S)$, $t_{\text{max}} = \text{max}(T)$ and $q = \mathcal{F}_L^+\mathbb{Q}(S, T) \geq 0$. Since $s_{\text{max}} \in S$ we can find $t \in T$ within q of s_{max} , and then $s_{\text{max}} \leq t + q \leq t_{\text{max}} + q$ and $s_{\text{max}} \dot{-} t_{\text{max}} \leq q$.

Using Proposition 5.7 and Lemma 7.7, the first of the following two commutative squares lifts to the second.

$$\begin{array}{ccc}
 \mathcal{F}_C^+ \mathbb{Q} & \xrightarrow{\max} & \mathbb{Q} \\
 \text{Id} \downarrow & & \downarrow \text{Id} \\
 \mathcal{F}_L^+ \mathbb{Q} & \xrightarrow{\max} & \overrightarrow{\mathbb{Q}}
 \end{array}
 \qquad
 \begin{array}{ccc}
 V^+ \mathbb{R} & \xrightarrow{\sup} & \mathbb{R} \\
 \Downarrow & & \downarrow \\
 P_L^+ \mathbb{R} & \xrightarrow{\overline{\max}} & \overrightarrow{(-\infty, \infty]}
 \end{array}$$

Since $K \subseteq L$ we have $\Downarrow K \sqsubseteq \Downarrow L$, and it follows that $\downarrow \sup(K) \sqsubseteq \downarrow \sup(L)$. This says that $\sup(L)$ has the larger left half in its Dedekind section, in other words that $\sup(K) \leq \sup(L)$. \square

We can similarly show that $\inf(K) \geq \inf(L)$, but this time the proof has to use the upper powerlocale.

The proofs show something of the reason why we need points of the Vietoris powerlocale if we are to calculate \sup and \inf . Given a point of the lower powerlocale, we can approximate its \sup from below but not from above. This gives a point of $\overrightarrow{(-\infty, \infty]}$, which in fact is what $\overline{\max}$ calculates in the above proof. Similarly, we can approximate its \inf from above but not below, getting a point in the dual $\overleftarrow{(-\infty, \infty)}$ (completing the dual metric $\overleftarrow{\mathbb{Q}}(x, y) = y \dot{-} x$). The same applies to points of the upper powerlocale, but the other way round. To get \sup and \inf as full Dedekind sections, approximated from both below and above, we need to start with a point of the Vietoris powerlocale.

Putting all these together, we obtain

Theorem 7.9 *There are maps $\sup, \inf: V^+ \mathbb{R} \rightarrow \mathbb{R}$ such that $\sup(K)$ is the greatest point in K and $\inf(K)$ is the least.*

7.2 The Heine–Borel maps

If $x \leq y$ are reals then the Heine–Borel Theorem says that the closed interval $[x, y]$ is compact. As it happens, it is also overt and semifitted, and so corresponds to a point $HB_C(x, y)$ of $V^+ \mathbb{R}$. In fact, this gives a continuous map $HB_C: \leq \rightarrow V^+ \mathbb{R}$. To see continuity, first note that if U is open, then $[x, y] \subseteq U$ iff there is some rational open interval $(p, q) \subseteq U$ containing both x and y . Hence $HB_C^{-1}(\square U) = \bigvee \{(p, \infty) \times (-\infty, q) \mid p < q, (p, q) \subseteq U\}$. Next, $[x, y]$ meets U iff there is some

rational open interval $(p, q) \leq U$ such that $x < q$ and $p < y$, so $HB_C^{-1}(\diamond U) = \bigvee \{(-\infty, q) \times (p, \infty) \mid p < q, (p, q) \leq U\}$.

We shall turn this argument on its head. Suppose we can define a map $HB_C: \leq \rightarrow V^+\mathbb{R}$, and show that $HB_C(x, y)$ corresponds to the subspace $[x, y]$ for reals $x \leq y$. Then we have shown that $[x, y]$ is always compact.

Remark 7.10 $[0, 1]$ is homeomorphic to $\overline{(0, 1) \cap \mathbb{Q}}$, after which its compactness follows by Theorem 6.7 from the fact that $(0, 1) \cap \mathbb{Q}$ is totally bounded. A similar technique works for other closed intervals. In fact in the case where $x < y$ we have $[x, y] \cong [0, 1]$. Hence our metric space techniques already give a proof of the localic Heine–Borel.

The paper [38] (written as a sequel to the present paper, though published earlier) shows that HB_C factors via a new powerlocale $V^c\mathbb{R}$ whose points are *connected* points of $V^+\mathbb{R}$ (in fact it gives a homeomorphism $\leq \cong V^c\mathbb{R}$). It exploits HB_C in its discussion of the Intermediate Value Theorem and Rolle’s Theorem.

To define HB_C it will be convenient also to use two simpler maps $HB_L = \Downarrow \circ HB_C$ and $HB_U = \Uparrow \circ HB_C$, taking their values in $P_L\mathbb{R}$ and $P_U\mathbb{R}$.

To find the closed interval $[x, y]$ as a point of a powerlocale, our working in effect requires us to define the “upper” and “lower” distances from S to $[x, y]$ for every finite $S \subseteq \mathbb{Q}$. In classical terms these would appear as $\sup_{z \in [x, y]} \min_{s \in S} d(s, z)$ and $\max_{s \in S} \inf_{z \in [x, y]} d(s, z)$. The upper distance is less than q iff every z in $[x, y]$ is within q of some s in S , in other words $\{B_q(s) \mid s \in S\}$ covers $[x, y]$. The lower distance is less than q iff every s in S is in the interval $(x - q, y + q)$. However, we must express these geometrically.

Definition 7.11 Let $x \leq y$ be reals, and let S be a non-empty finite subset of $\mathbb{Q} \times \mathbb{Q}_+$. We say that $\{B_\varepsilon(s) \mid (s, \varepsilon) \in S\}$ covers $[x, y]$ if there is some non-empty finite sequence (s_i, ε_i) ($1 \leq i \leq n$) in S such that

$$\begin{aligned} s_1 - \varepsilon_1 &< x \\ s_{i+1} - \varepsilon_{i+1} &< s_i + \varepsilon_i \quad (1 \leq i < n) \\ y &< s_n + \varepsilon_n \end{aligned}$$

It is simpler for us not to assume that $s_1 \leq s_2 \leq \dots \leq s_n$. It could be that the ball $B_{\varepsilon_{i+1}}(s_{i+1})$ is a long way to the left of $B_{\varepsilon_i}(s_i)$ with a big gap in between. For present purposes it turns out not to matter, though [38] also shows that a better behaved subsequence can always be found.

Lemma 7.12 Suppose $\{B_\varepsilon(s) \mid (s, \varepsilon) \in S\}$ covers $[x, y]$ with a sequence (s_i, ε_i) as described. Suppose also $x \leq z \leq y$. Then for some i we have $s_i - \varepsilon_i < z < s_i + \varepsilon_i$.

Proof The sequence also covers $[x, z]$, for $z \leq y < s_n + \varepsilon_n$ implies $z < s_n + \varepsilon_n$. (Proof: choose a rational q such that $y < q < s_n + \varepsilon_n$. Then we have either $z < s_n + \varepsilon_n$, as desired, or $q < z$. But this second alternative implies $y < z$, which is impossible.) Hence without loss of generality we can assume that $z = y$. By a similar argument we can furthermore assume that $x = z$ and the closed interval is a single point. We use induction on n . If $n = 1$ then we have $s_1 - \varepsilon_1 < z < s_1 + \varepsilon_1$ and we are done. Now suppose $n > 1$. Since $s_n - \varepsilon_n < s_{n-1} + \varepsilon_{n-1}$, we have either $s_n - \varepsilon_n < z$, in which case we can take $i = n$, or $z < s_{n-1} + \varepsilon_{n-1}$, in which case we can use induction. \square

It is clear that if we have a cover and we enlarge all the balls then we still have a cover; and also that we are able to shrink the balls slightly and still have a cover.

Recall the natural transformations ϕ_\sim from Definition 4.4.

Definition 7.13 Let $x \leq y$ be reals. Then we define subsets $\text{HB}_\sim(x, y)$ of $\mathcal{F}^+\mathbb{Q} \times \mathcal{Q}_+$ by

$$\begin{aligned} B_\delta(S) &\in \text{HB}_U(x, y) \text{ iff } \phi(B_\delta(S)) \text{ covers } [x, y] \\ B_\delta(S) &\in \text{HB}_L(x, y) \text{ iff } \forall s \in S. (x < s + \delta \wedge s - \delta < y) \\ \text{HB}_C(x, y) &= \text{HB}_U(x, y) \cap \text{HB}_L(x, y) \end{aligned}$$

The condition for $\text{HB}_L(x, y)$ is stating that each $B_\delta(s)$ overlaps $[x, y]$: for it would fail to overlap iff $s + \delta \leq x$ or $y \leq s - \delta$.

Lemma 7.14 Suppose $x \leq y$ are reals, $S, T \in \mathcal{F}^+\mathbb{Q}$, $B_\delta(S) \in \text{HB}_U(x, y)$ and $B_\varepsilon(T) \in \text{HB}_L(x, y)$. Then

$$\mathcal{F}_U\mathbb{Q}(S, T) = \mathcal{F}_L\mathbb{Q}(T, S) < \delta + \varepsilon.$$

Proof The first equality is immediate from the symmetry of our gms structure on \mathbb{Q} . If $t \in T$ then t is in the open interval $(x - \varepsilon, y + \varepsilon)$. However, the closed interval $[x - \varepsilon, y + \varepsilon]$ is covered by $\{B_{\delta+\varepsilon}(s) \mid s \in S\}$, and so by Lemma 7.12 there is some $s \in S$ with $s - \delta - \varepsilon < t < s + \delta + \varepsilon$. Hence $\mathcal{F}_U\mathbb{Q}(S, T) < \delta + \varepsilon$. \square

Lemma 7.15 Let $x \leq y$ be reals and let $\varepsilon \in \mathcal{Q}_+$. Then there is some $S \in \mathcal{F}^+\mathbb{Q}$ such that $B_\varepsilon(S) \in \text{HB}_C(x, y)$.

Proof Choose rationals a and b with $a < x < a + \varepsilon$ and $b - \varepsilon < y < b$. Now choose some natural number $k \geq 1$ such that $\mu < 2\varepsilon$, where $\mu = (b - a)/k$. If we divide the interval (a, b) into k equal parts, each of length μ , then their centres are

$$s_i = a + (2i - 1)\mu/2 \quad (1 \leq i \leq k).$$

Let $S = \{s_i \mid 1 \leq i \leq k\}$. □

Lemma 7.16 *Suppose $x \leq y$ are reals, and suppose (with \sim being either U, L or C) we have*

$$B_{\delta_\lambda}(S_\lambda) \in \text{HB}_{\sim}(x, y) \quad (\lambda = 1, 2).$$

Then there is some $B_\varepsilon(T) \in \text{HB}_C(x, y)$ such that $\mathcal{F}_{\sim}\mathbb{Q}(S_\lambda, T) + \varepsilon < \delta_\lambda$.

Proof We can find ε such that $B_{\delta_\lambda - 2\varepsilon}(S_\lambda) \in \text{HB}_{\sim}(x, y)$ for $\lambda = 1, 2$. By Lemma 7.15 we can find T with $B_\varepsilon(T) \in \text{HB}_C(x, y)$. Now by Lemma 7.14 if \sim is U or L we deduce

$$\mathcal{F}_{\sim}\mathbb{Q}(S_\lambda, T) < \delta_\lambda - 2\varepsilon + \varepsilon = \delta_\lambda - \varepsilon.$$

The case when \sim is C follows. □

Proposition 7.17 *The definitions above define maps $\text{HB}_{\sim}: \leq \rightarrow \overline{\mathcal{F}_{\sim}^+\mathbb{Q}}$ (with \sim being U, L or C).*

Proof We must show that $\text{HB}_{\sim}(x, y)$ is a Cauchy filter. Upper closedness is obvious, and binary filteredness and the Cauchy property follow from Lemmas 7.16 and 7.15. □

Lemma 7.18 *Let $x \leq y$ be reals. Then*

- (1) $\Downarrow \text{HB}_C(x, y) = \text{HB}_L(x, y)$ and
- (2) $\Uparrow \text{HB}_C(x, y) = \text{HB}_U(x, y)$.

Proof By Proposition 5.7 and Definition 2.20 we must show that (with \sim standing for L or U) $\text{HB}_{\sim}(x, y) = (\supset \text{HB}_C(x, y))$, where \supset is the ball refinement of $\mathcal{F}_{\sim}\mathbb{Q}$. This follows from Lemma 7.16. □

Theorem 7.19 *If $x \leq y$ are reals, then $\text{HB}_{\sim}(x, y)$, as point of $P_{\sim}\mathbb{R}$, corresponds to the closed interval sublocale $[x, y]$.*

Proof When \sim is U: We show that a point z of \mathbb{R} has $\uparrow z \sqsupseteq \text{HB}_U(x, y)$ iff $x \leq z \leq y$. We have that $\uparrow z \sqsupseteq \text{HB}_U(x, y)$ iff whenever $\{B_\varepsilon(s) \mid s \in S\}$ covers $[x, y]$ then z is in $B_\varepsilon(s)$ for some s in S . That this is implied by $x \leq z \leq y$ has already been proved in Lemma 7.12. For the converse we wish to show $x \leq z$, ie that (x, z) is in the closed complement of the open sublocale $>$ of \mathbb{R}^2 , so suppose $z < q < x$ for some rational q . Choosing also a rational $r > y$ such that $r > q$, the ball $B_{(r-q)/2}((q+r)/2)$ covers $[x, y]$ but does not contain z . Similarly, $z \leq y$.

When \sim is L: We show that a point z of \mathbb{R} has $\downarrow z \sqsubseteq \text{HB}_L(x, y)$ iff $x \leq z \leq y$. We have that $\downarrow z \sqsubseteq \text{HB}_L(x, y)$ iff whenever $s - \varepsilon < z < s + \varepsilon$ then $x < s + \varepsilon$ and $s - \varepsilon < y$. This is obviously implied by $x \leq z \leq y$. For the converse, if $z < x$ then we can find rationals q and r with $q < z < r < x$ and then by taking $s = q$ and $\varepsilon = r - q$ we get a contradiction. Hence $x \leq z$, and similarly $z \leq y$.

When \sim is C: For any locale X , the sublocale corresponding to a point K of VX is the sublocale meet of those corresponding to $\uparrow K$ and $\downarrow K$. Hence by Lemma 7.18, the sublocale corresponding to $\text{HB}_C(x, y)$ is the meet of those for $\text{HB}_U(x, y)$ and $\text{HB}_L(x, y)$, so it is just $[x, y]$ again. \square

Corollary 7.20 (Heine-Borel Theorem) *If x and y are reals, then the closed interval $[x, y]$ is compact.*

Proof This follows already from part (U) of the Theorem 7.19, since the points of $P_U\mathbb{R}$ are equivalent to compact fitted sublocales of \mathbb{R} . \square

Example 7.21 Let $f: \mathbb{R} \rightarrow \mathbb{R}$ be a map. Then we can define $\sup_{x \leq z \leq y} f(z)$ (as a continuous function of x and y) locally as the composite map

$$\text{HB}_C; V^+f; \text{sup}: \leq \rightarrow V^+\mathbb{R} \rightarrow V^+\mathbb{R} \rightarrow \mathbb{R}.$$

The main technical question here is how we know V^+f takes points of $V^+\mathbb{R}$ to their sublocale images under f . This is discussed in more detail in [38].

Remark 7.22 We have defined $\text{HB}_\sim(x, y)$ in the case where $x \leq y$. One might consider it natural to extend this so that $\text{HB}_\sim(x, y)$ is empty if $x > y$, but a simple argument shows this is impossible for HB_L and HB_C . Consider the point \emptyset . It is bottom in P_LX and isolated in VX , and in each case $\{\emptyset\}$ is closed. Hence $\text{HB}_L^{-1}(\{\emptyset\})$ and $\text{HB}_C^{-1}(\{\emptyset\})$ would also have to be closed; but our ambition was to have them equal to $>$, which is open but not closed.

In P_UX on the other hand, \emptyset is the top point and $\{\emptyset\}$ is open. We sketch a modified construction of HB_U that extends it to a map $\mathbb{R} \times \mathbb{R} \rightarrow \overline{\mathcal{F}_U\mathbb{Q}}$ in the way suggested.

We generalize the previous definition of “covers” to say that, for S a finite subset of $\mathbb{Q} \times \mathbb{Q}_+$, $\{B_\varepsilon(s) \mid (s, \varepsilon) \in S\}$ covers $[x, y]$ iff either $x > y$ or it has a non-empty finite sequence with the property described before. (Note that in this second case we still do not assume $x \leq y$.)

The proof of Proposition 7.17 must now be modified slightly. For the Cauchy property, if $\varepsilon \in \mathbb{Q}_+$ then we find rationals a and b with $a < x$ and $b > y$. Without loss of generality we can suppose $a < b$. By Lemma 7.15 we can then find U with $B_\varepsilon(U) \in \text{HB}_C(a, b) \subseteq \text{HB}_U(a, b) \subseteq \text{HB}_U(x, y)$.

For binary filteredness, suppose $B_{\delta_\lambda}(S_\lambda) \in \text{HB}_U(x, y)$ ($\lambda = 1, 2$). We can find $\varepsilon' \in \mathbb{Q}_+$ with $B_{\delta_\lambda - 2\varepsilon'}(S_\lambda) \in \text{HB}_U(x, y)$. We shall now find $B_\varepsilon(T)$ such that $B_\varepsilon(T) \in \text{HB}_U(x, y)$ and $\mathcal{F}_U\mathbb{Q}(S_\lambda, T) + \varepsilon < \delta_\lambda$. If $x > y$ then we can choose $T = \emptyset$ and $\varepsilon = \varepsilon'$. In the other case, we have covering sequences $((s_i^\lambda, \delta_\lambda - 2\varepsilon'))_{1 \leq i \leq m_\lambda}$ taken from S_λ . Let

$$a = \max_\lambda (s_1^\lambda - \delta_\lambda + 2\varepsilon') < x$$

$$b = \min_\lambda (s_{m_\lambda}^\lambda + \delta_\lambda - 2\varepsilon') > y.$$

Note that $B_{\delta_\lambda - \varepsilon'}(S_\lambda) \in \text{HB}_U(a, b)$. If $b < a$ then $y < x$, so (since the order is decidable on \mathbb{Q}) we can assume $a \leq b$, and then by Lemma 7.16 we can find

$$B_\varepsilon(T) \in \text{HB}_C(a, b) \subseteq \text{HB}_U(a, b) \subseteq \text{HB}_U(x, y)$$

such that

$$\mathcal{F}_U\mathbb{Q}(S_\lambda, T) + \varepsilon < \delta_\lambda - \varepsilon' < \delta_\lambda.$$

Martín Escardó has pointed out that in some situations it is useful to precompose HB_\sim with $\langle \min, \max \rangle: \mathbb{R} \times \mathbb{R} \rightarrow \leq$, thus recovering a map with domain $\mathbb{R} \times \mathbb{R}$. (This does not recover the HB_U defined above, of course.)

8 Conclusions

We have presented a constructive, localic account of hyperspace techniques for dealing with certain kinds of subspaces of complete metric spaces. Our account is very general, covering localic completions of generalized metric spaces in the sense of Lawvere [14], and it uses that generality to include the lower and upper powerlocales (localic hyperspaces) where the metric is necessarily asymmetric. The techniques are computationally convenient, as illustrated by the applications here. As applied to compact intervals in the reals, they have been extended [38] to discuss connectedness

and give constructive localic accounts of the Intermediate Value Theorem and Rolle's Theorem.

Our results are analogues of existing classical, spatial results ([2], [3], [20]). [2] discusses powerdomains for completions of generalized metric spaces, and shows that they too are completions of spaces of finite subsets. However, their classical proofs are based on a definition of completion as closure by limits within a space of modules. Our constructive, localic results, though clearly analogous, are quite different in their techniques and technical content even when viewed in terms of points. Our completion (from [33]) is defined with a direct representation of the points as Cauchy filters, and for our analogues of the powerdomains defined in [2] we have been able to exploit the established theory of powerlocales.

One constructivist aspect of the results is that they indicate how to get good *predicative* tools for dealing with these powerlocales. The definition of powerlocale uses the frame of opens of X as a set of generators for $P_U X$ or $P_L X$, and on the face of it this underlay our treatment particularly in Section 5.1. This is topos-valid, but not predicative, since the construction of the frame of opens requires the powerset axiom. However, there are predicative approaches for extracting generators and relations for powerlocales out of those for the original locale, and some of these are set out (in the context of predicative formal topology) in [35] and [34]. In fact, our proofs in Section 5.1 could be made compatible with that development. When translated thus into predicative mathematics the general results can be complicated to use. We have here transformed them into a special form that applies in the case of gms completion and naturally extends conventional ideas using the Hausdorff metric.

Finally, it is natural to wonder whether the technical development can be simplified, perhaps avoiding the lengthy detour via continuous dcpos and the ball domain, or perhaps making better use of the pointwise reasoning techniques (in a point-free setting) of geometric logic. I would hope it can, but in the 10 years since [29] was issued I have not managed to simplify the overall argument despite having tidied the proofs considerably. Nonetheless, the use of ball domains does show connections with a technique (see [3]) that has already had some success in relating computation and domain theory to metric spaces. As for the pointwise reasoning, this seems to call for better ideas than have so far come to me. Even for the particular case of $V\mathbb{R}$, the classical equivalence between compact subspaces and points of $\overline{\mathcal{F}_C\mathbb{Q}}$ (see [38]) is intricate and does not seem to have an analogue in geometric reasoning.

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School of Computer Science, University of Birmingham
Birmingham B15 2TT, UK

s.j.vickers@cs.bham.ac.uk

<http://www.cs.bham.ac.uk/~sjv>